

FIG. 1

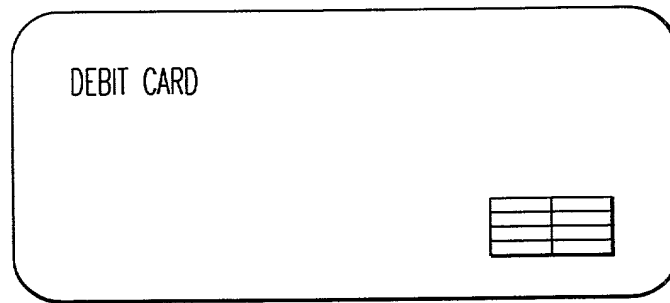


FIG. 2

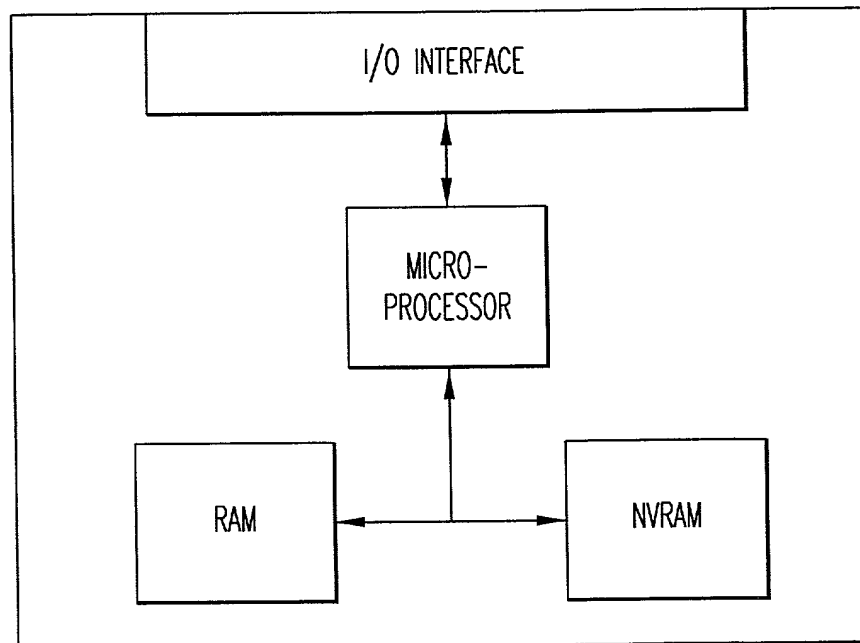


FIG. 3

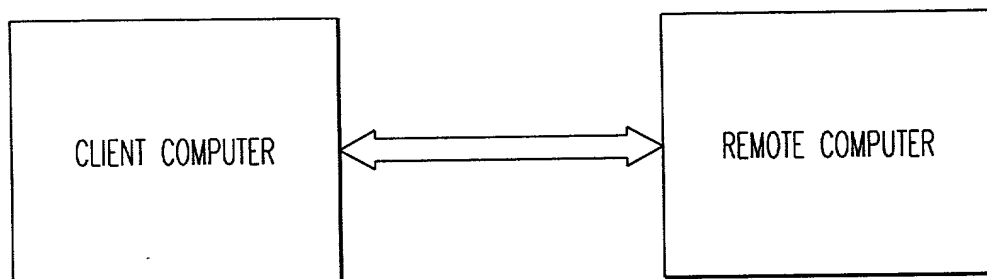


FIG. 4



FIG. 5A

FIG. 5C

INPUT STATE	0	1	2
0	(1,1)	(2,2)	(0,2)
1	(1,1)	(1,2)	(0,0)
2	(2,2)	(2,2)	(2,2)

FIG. 5B

INPUT STATE	0	1	2
0	(1,1)	(2,2)	(0,2)
1	(1,1)	(1,2)	(0,0)
2	(2,2)	—	(2,2)

FIG. 5D

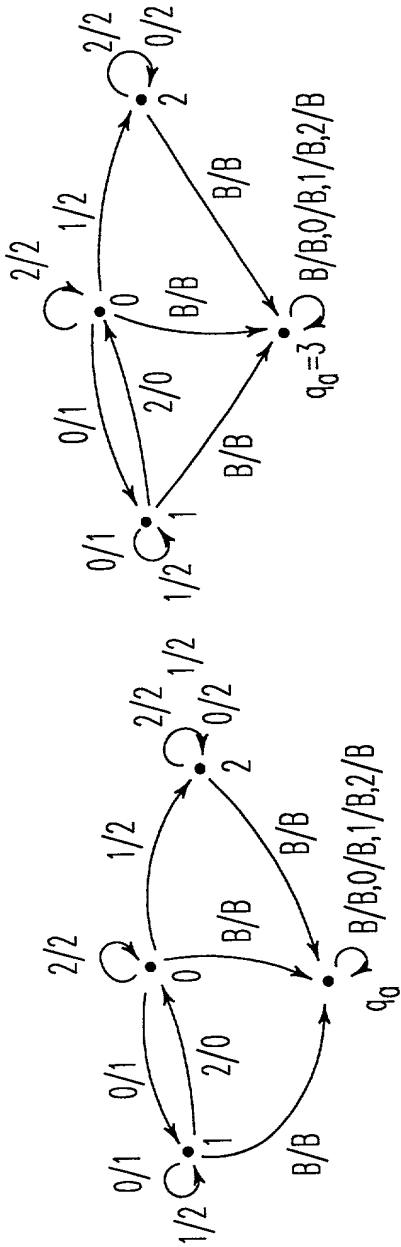


FIG. 6C

FIG. 6A

CORRESPONDING FUNCTION TABLE

INPUT STATE	0	1	2	B
0	(1,1)	(2,2)	(0,2)	(3,B)
1	(1,1)	(1,2)	(0,0)	(3,B)
2	(2,2)	—	(2,2)	(3,B)
$q_0=3$	(3,B)	(3,B)	(3,B)	(3,B)

CORRESPONDING FUNCTION TABLE

INPUT STATE	0	1	2	B
0	(1,1)	(2,2)	(0,2)	(q_0 ,B)
1	(1,1)	(1,2)	(0,0)	(q_0 ,B)
2	(2,2)	(2,2)	(2,2)	(q_0 ,B)
q_0	(q_0 ,B)	(q_0 ,B)	(q_0 ,B)	(q_0 ,B)

FIG. 6D

FIG. 6B

$$\left\{ \begin{array}{l} \text{INPUT SPACE: } \Sigma' = \{0, 1, 2, B\} \\ \text{STATE SPACE: } Q' = \{0, 1, 2, q_0\}, \quad q_0 = 3 \\ \text{OUTPUT SPACE: } \Delta' = \{0, 1, 2, 3\} \\ \\ \text{VECTORIZATION EXAMPLE FOR } N=2: \\ \text{INPUT SPACE: } \Sigma' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(1,0)}, \overset{B}{(1,1)} \} \\ \text{STATE SPACE: } Q' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(1,0)}, \overset{q_0=3}{(1,1)} \} \\ \text{OUTPUT SPACE: } \Delta' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(1,0)}, \overset{3}{(1,1)} \} \end{array} \right.$$

FIG. 7A

$$\left\{ \begin{array}{l} \text{VECTORIZATION EXAMPLE FOR } N=3: \\ \text{INPUT SPACE: } \Sigma' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(0,2)}, \overset{B}{(1,0)} \} \\ \text{STATE SPACE: } Q' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(0,2)}, \overset{q_0=3}{(1,0)} \} \\ \text{OUTPUT SPACE: } \Delta' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(0,2)}, \overset{B}{(1,0)} \} \end{array} \right.$$

FIG. 7B

$$\left\{ \begin{array}{l} \text{VECTORIZATION EXAMPLE FOR } N \geq 4 \\ \text{INPUT SPACE: } \Sigma' = \{ \overset{0}{(0)}, \overset{1}{(1)}, \overset{2}{(2)}, \overset{B}{(3)} \} \\ \text{STATE SPACE: } Q' = \{ \overset{0}{(0)}, \overset{1}{(1)}, \overset{2}{(2)}, \overset{q_0=3}{(3)} \} \\ \text{OUTPUT SPACE: } \Delta' = \{ \overset{0}{(0)}, \overset{1}{(1)}, \overset{2}{(2)}, \overset{3}{(3)} \} \end{array} \right.$$

FIG. 7C

■

 q_d

FIG. 9A

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)	(1,1)	(1,2)	(2,0)	(2,1)	(2,2)
(0,0)	((0,1),(0,1))	((0,2),(0,2))	((0,0),(0,2))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(0,1)	((0,1),(0,1))	((0,1),(0,2))	((0,0),(0,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(0,2)	((0,2),(0,2))	((1,0),(1,0))	((0,2),(0,2))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(1,0)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(1,1)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(1,2)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(2,0)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(2,1)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(2,2)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))

FIG. 9B

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)	(1,1)	(1,2)	(2,0)	(2,1)	(2,2)
(0,0)	((0,1),(0,1))	((0,2),(0,2))	((0,0),(0,2))	((1,0),(1,0))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))
(0,1)	((0,1),(0,1))	((0,1),(0,2))	((0,0),(0,0))	((1,0),(1,0))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))
(0,2)	((0,2),(0,2))	((*,*)(*,*))	((0,2),(0,2))	((1,0),(1,0))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))
(1,0)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))
(1,1)	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))
(1,2)	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))
(2,0)	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))
(2,1)	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))
(2,2)	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))	((*,*)(*,*))

FIG. 10

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	((0,1),(0,1))	((0,2),(0,2))	((0,0),(0,2))	((1,0),(1,0))
(0,1)	((0,1),(0,1))	((0,1),(0,2))	((0,0),(0,0))	((1,0),(1,0))
(0,2)	((0,2),(0,2))	————	((0,2),(0,2))	((1,0),(1,0))
(1,0)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(1,1)				

FIG. 11A

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	((0,1),(0,1))	((0,2),(0,2))	((0,0),(0,2))	((1,0),(1,0))
(0,1)	((0,1),(0,1))	((0,1),(0,2))	((0,0),(0,0))	((1,0),(1,0))
(0,2)	((0,2),(0,2))	————	((0,2),(0,2))	((1,0),(1,0))
(1,0)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(1,1)	((0,1),(0,1))	((0,1),(0,2))	((0,0),(0,0))	((1,0),(1,0))

FIG. 11B

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	((0,1),(0,1))	((0,2),(0,2))	((0,0),(0,2))	((1,0),(1,0))
(0,1)	((0,1),(0,1))	((0,1),(0,2))	((0,0),(0,0))	((1,0),(1,0))
(0,2)	((0,2),(0,2))	————	((0,2),(0,2))	((1,0),(1,0))
(1,0)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(1,1)	((0,1),(0,1))	((0,1),(0,2))	((0,0),(0,0))	((1,0),(1,0))

FIG. 12A

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	((0,1),(0,1))	((0,2),(0,2))	((0,0),(0,2))	((1,0),(1,0))
(0,1)	((0,1),(0,1))	((1,1),(0,2))	((0,0),(0,0))	((1,0),(1,0))
(0,2)	((0,2),(0,2))	————	((0,2),(0,2))	((1,0),(1,0))
(1,0)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
(1,1)	((0,1),(0,1))	((0,1),(0,2))	((0,0),(0,0))	((1,0),(1,0))

FIG. 12B

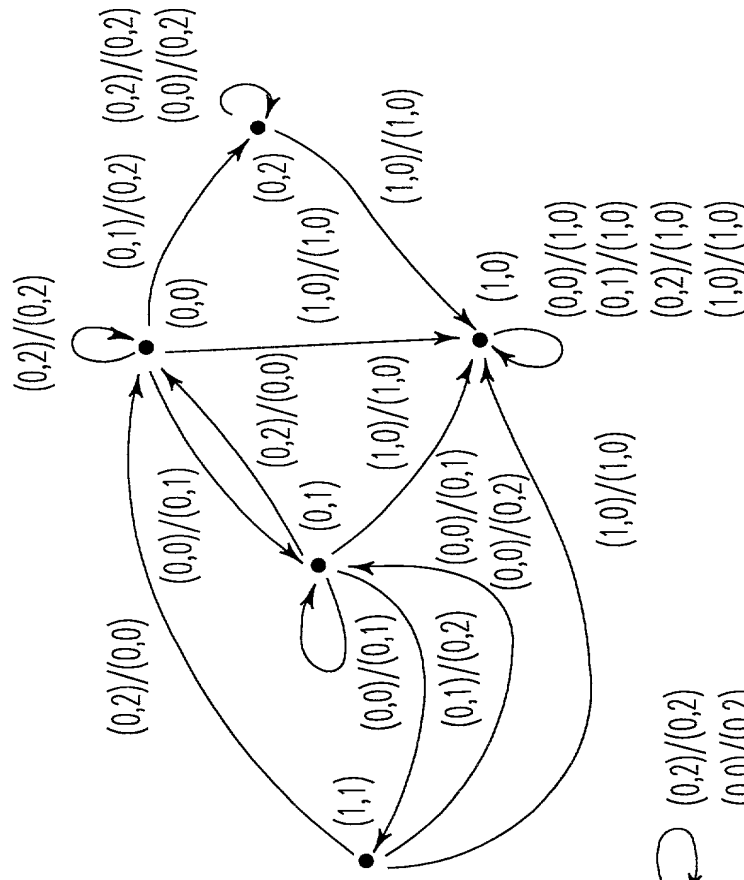


FIG. 12D

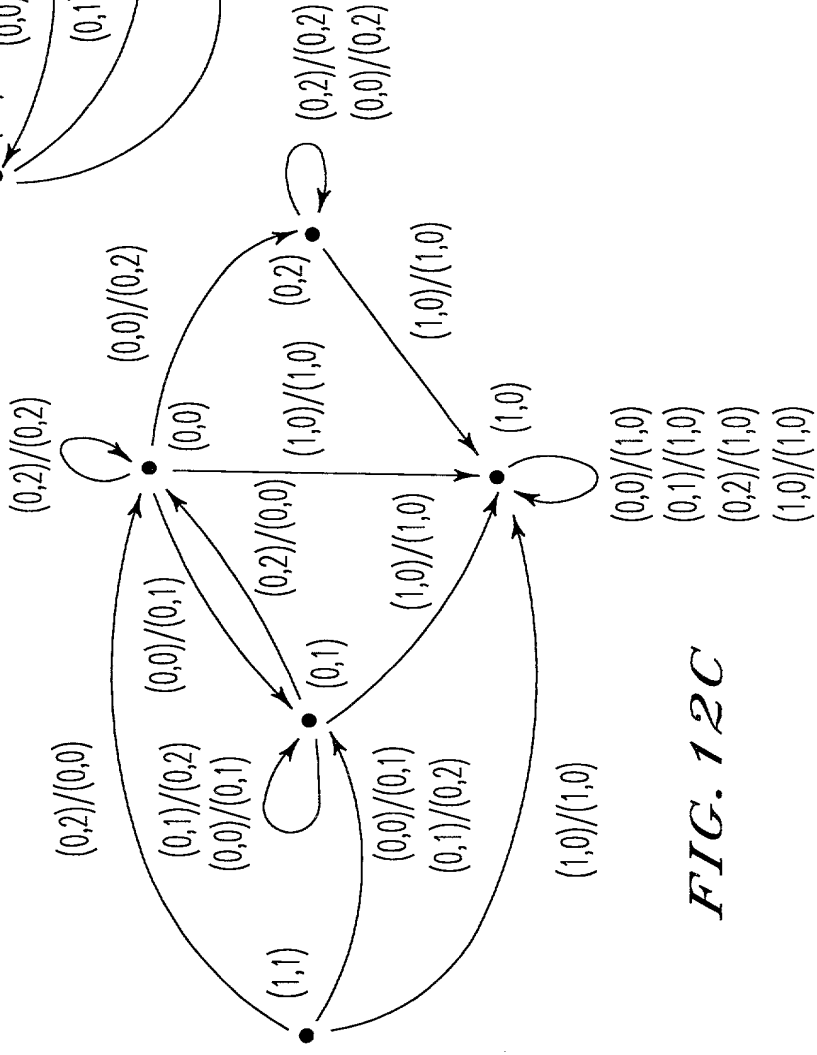


FIG. 12C

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((0,1),(0,1))$	$((0,2),(0,2))$	$((0,0),(0,2))$	$((1,0),(1,0))$
(0,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$
(0,2)	$((0,2),(0,2))$	————	$((0,2),(0,2))$	$((1,0),(1,0))$
(1,0)	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$
(1,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$

FIG. 13A

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((1,0),(0,1))$	$((0,2),(0,2))$	$((0,0),(0,2))$	$((0,1),(1,0))$
(0,1)	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$
(0,2)	$((0,2),(0,2))$	————	$((0,2),(0,2))$	$((0,1),(1,0))$
(1,0)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,0),(0,0))$	$((0,1),(1,0))$
(1,1)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,0),(0,0))$	$((0,1),(1,0))$

FIG. 13B

STATE \ INPUT	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((1,0),(0,1))$	$((0,2),(0,2))$	$((0,0),(0,2))$	$((0,1),(1,0))$
(0,1)	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$
(0,2)	$((0,2),(0,2))$	—	$((0,2),(0,2))$	$((0,1),(1,0))$
(1,0)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,0),(0,0))$	$((0,1),(1,0))$
(1,1)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,0),(0,0))$	$((0,1),(1,0))$

FIG. 14A

STATE \ INPUT	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((1,0),(0,1))$	$((0,2),(0,2))$	$((0,1),(1,0))$	$((0,0),(0,2))$
(0,1)	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$
(0,2)	$((0,2),(0,2))$	—	$((0,1),(1,0))$	$((0,2),(0,2))$
(1,0)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,1),(1,0))$	$((0,0),(0,0))$
(1,1)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,1),(1,0))$	$((0,0),(0,0))$

FIG. 14B

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	((1,0),(0,1))	((0,2),(0,2))	((0,1),(1,0))	((0,0),(0,2))
(0,1)	((0,1),(1,0))	((0,1),(1,0))	((0,1),(1,0))	((0,1),(1,0))
(0,2)	((0,2),(0,2))	—	((0,1),(1,0))	((0,2),(0,2))
(1,0)	((1,0),(0,1))	((1,0),(0,2))	((0,1),(1,0))	((0,0),(0,0))
(1,1)	((1,0),(0,1))	((1,0),(0,2))	((0,1),(1,0))	((0,0),(0,0))

FIG. 15A

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	((1,0),(0,1))	((0,2),(1,0))	((0,1),(0,2))	((0,0),(1,0))
(0,1)	((0,1),(0,2))	((0,1),(0,2))	((0,1),(0,2))	((0,1),(0,2))
(0,2)	((0,2),(1,0))	—	((0,1),(0,2))	((0,2),(1,0))
(1,0)	((1,0),(0,1))	((1,0),(1,0))	((0,1),(0,2))	((0,0),(0,0))
(1,1)	((1,0),(0,1))	((1,0),(1,0))	((0,1),(0,2))	((0,0),(0,0))

FIG. 15B

STATE \ INPUT	INPUT	
	(0,0)	
(0,0)	((0,1)(0,1))	

FIG. 16A

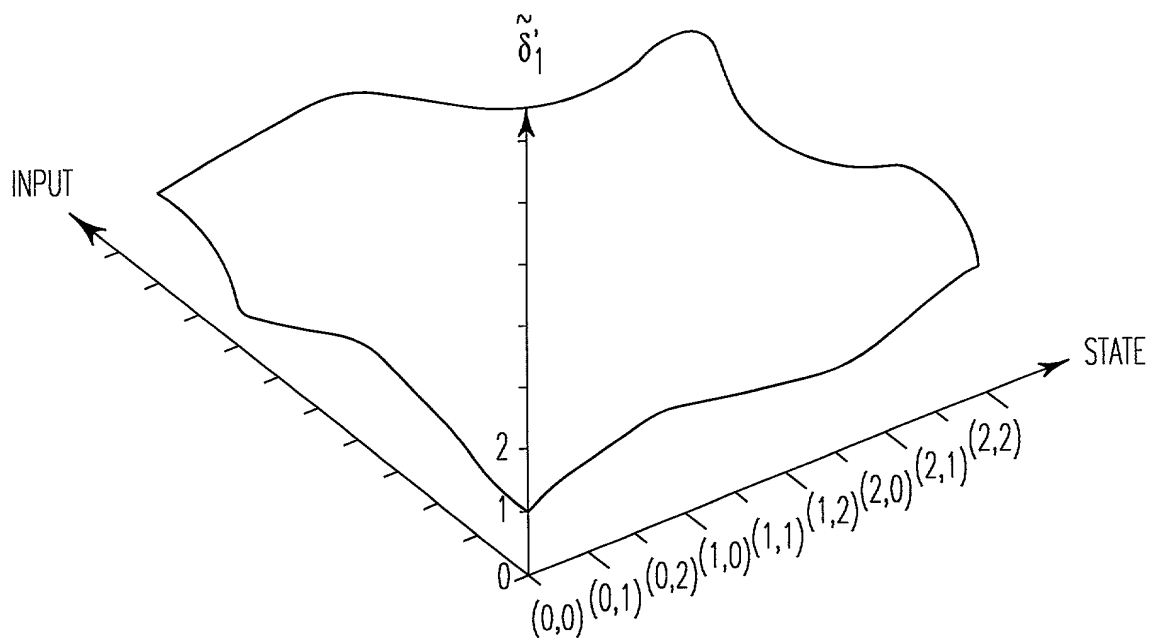


FIG. 16B

PRECALCULATE $a_k(x)$ FOR $k=\{0,1,2,4,5\} < \mathbb{Z}_{11}$.

PRECOMPUTATION RESULTS IN THE SERIES OF POLYNOMIALS

$$a_0(x)$$

$$a_1(x)$$

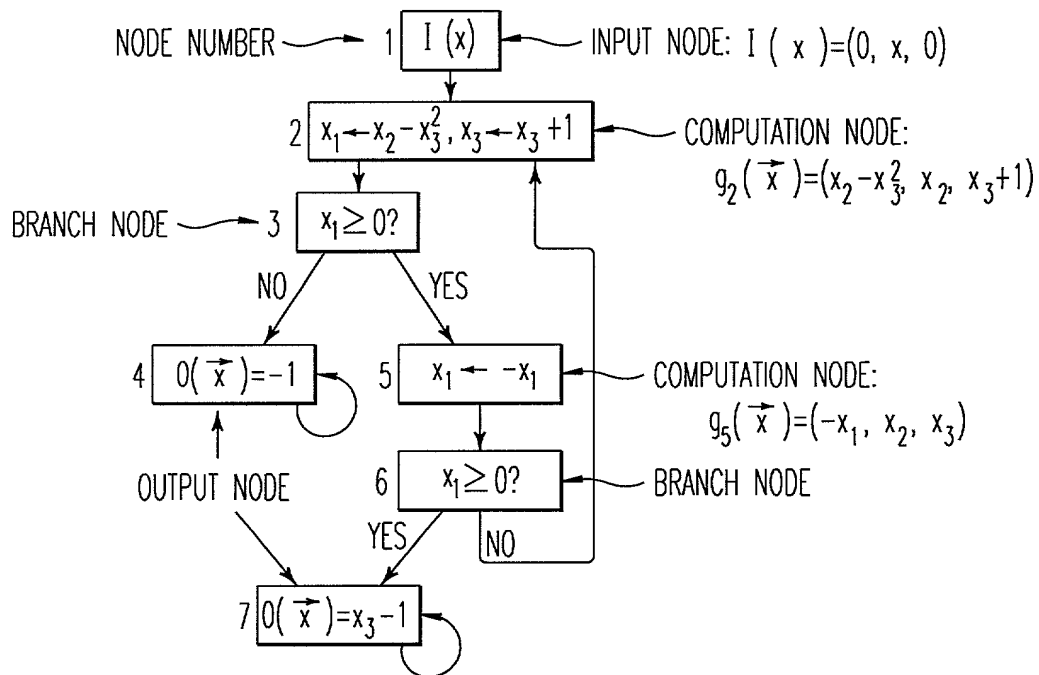
$$a_2(x)$$

$$a_4(x)$$

$$a_5(x)$$

REPRESENTED BY THEIR RESPECTIVE ARRAYS OF COEFFECIENTS

FIG. 17



- WHEN RESTRICTING A BSS MACHINE TO A FINITE FIELD \mathbb{Z}_N , THE CHOICE OF N IS DICTATED BY THE FOLLOWING:
 - 1) N MUST BE A PRIME NUMBER
 - 2) N MUST BE AT LEAST AS GREAT AS THE NUMBER OF NODES
 - 3) N MUST MAKE ALLOWANCE FOR CONSTANTS USED IN THE MACHINE
 - 4) N MUST ACCOMODATE USER REQUIREMENTS
- FOR THE ABOVE EXAMPLE:
 - N SATISFIES THE FIRST CONDITION IF IT IS EQUAL TO 2, 3, 5, 7, 11,...
 - N SATISFIES THE SECOND CONDITION IF IT IS ≥ 7
 - N THE GREATEST CONSTANTS HAVE ABSOLUTE VALUE 1, SO N SATISFIES THE THIRD CONDITION IF IT IS ≥ 2
 - IF THE USER REQUIRES THAT THE x INPUT MUST BE ABLE TO BE AS LARGE AS 100, N SATISFIES THE FOURTH CONDITION IF IT IS > 100 . THE LEAST N SATISFYING ALL FOUR CONDITIONS WOULD THEN BE $N=101$
- SINCE ALL MAPPINGS IN THE BSS MACHINE ABOVE ARE POLYNOMIAL, THE RESTRICTION OF COMPUTATION MAPPINGS TO POLYNOMIAL MAPPINGS IS ALREADY SATISFIED.
- THE NEW NODE-NUMBERING CONVENTION SIMPLY SUBTRACTS 1 FROM EACH NODE NUMBER, SUCH THAT NUMBERING BEGINS AT 0.

0	1	2	3	4	5	6	7
↓	↓	↓	↓	↓	↓	↓	↓
0	1	2	3	4	5	6	

FIG. 18

THE FULL STATE SPACE OF THE BSS MACHINE, AS ADAPTED SO FAR, IS:

$$\underbrace{\{0, \dots, 6\}}_{\text{NODE NUMBER SPACE}} \times \underbrace{\mathbb{Z}_N \times \mathbb{Z}_N \times \mathbb{Z}_N}_{\text{STATE SPACE}} \quad \text{CORRESPONDING VECTORS HAVE THE COMPONENTS:}$$

n	x ₁	x ₂	x ₃
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THE REVISED FULL STATE SPACE ADDS THE OUTPUT AND INPUT COMPONENTS:

$$\{0, \dots, 6\} \times \mathbb{Z}_N \times \mathbb{Z}_N \times \underbrace{\mathbb{Z}_N}_{\text{OUTPUT}} \times \underbrace{\mathbb{Z}_N}_{\text{INPUT}}$$

CORRESPONDING VECTORS HAVE THE COMPONENTS:

n	x ₁	x ₂	x ₃	x ₄	x ₅
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OUTPUT
INPUT

ALSO A COMPUTATION MAPPING g_i IS ADDED TO EVERY NODE THAT DOESN'T ALREADY HAVE ONE. THUS FOR EACH NODE VIEWED IN ISOLATION:

- NODE 0: $g_0(\vec{x}) = (0, x_5, 0, 0, x_5)$ IS ADDED
- NODE 1: "g₂" (NOW g_1) IS CHANGED TO $g_1(\vec{x}) = (x_2 - x_3^2, x_2, x_3 + 1, 0, x_5)$
- NODE 2: $g_2(\vec{x}) = (x_1, x_2, x_3, 0, x_5)$ IS ADDED
- NODE 3: $g_3(\vec{x}) = (x_1, x_2, x_3^{N-1}, x_5)$ IS ADDED
- NODE 4: g_4 (PREVIOUSLY "g₅") IS CHANGED TO $g_4(\vec{x}) = (-x_1, x_2, x_3, 0, x_5)$
- NODE 5: $g_5(\vec{x}) = (x_1, x_2, x_3, 0, x_5)$ IS ADDED
- NODE 6: $g_6(\vec{x}) = (x_1, x_2, x_3, x_3 - 1, x_5)$ IS ADDED

AS THE RELATION ≥ 0 HOLDS FOR ALL ELEMENTS IN \mathbb{Z}_N , IT IS REPLACED BY A SERIES OF SET INCLUSION RELATIONS. BECAUSE \mathbb{Z}_N DOES NOT HAVE NEGATIVE NUMBERS AS ELEMENTS, THE RELATIONS WILL NOT HAVE AN EXACT CORRESPONDENCE TO THE ORIGINAL RELATIONS. REASONABLE SET INCLUSION RELATIONS FOR THIS EXAMPLE ARE:

FOR NODE 2: $\in \mathbb{Z}_p - \{0\}$ WITH THE SAME MAPPING IN NODE 1 AS BEFORE.
 FOR NODE 5: $\in \{1\}$, CHANGING g_4 TO $g_4(\vec{x}) = (x_3 + 1, x_2, x_3, 0, x_5)$

FIG. 19

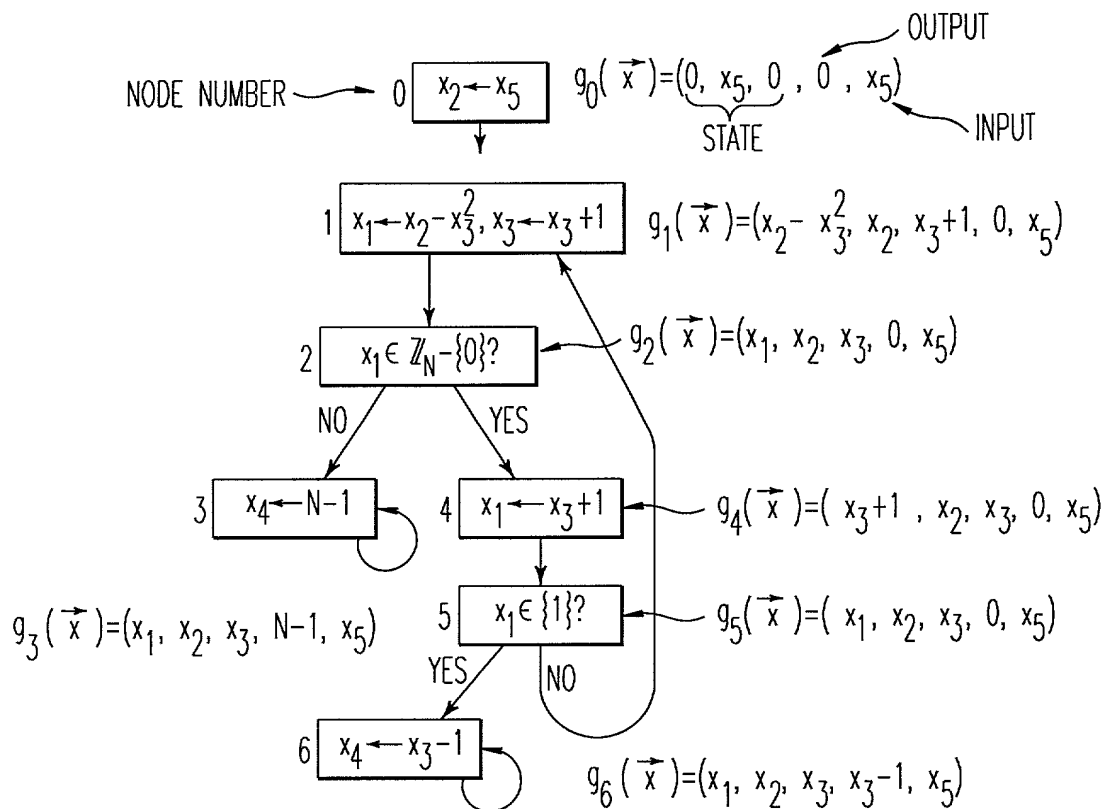


FIG. 20A

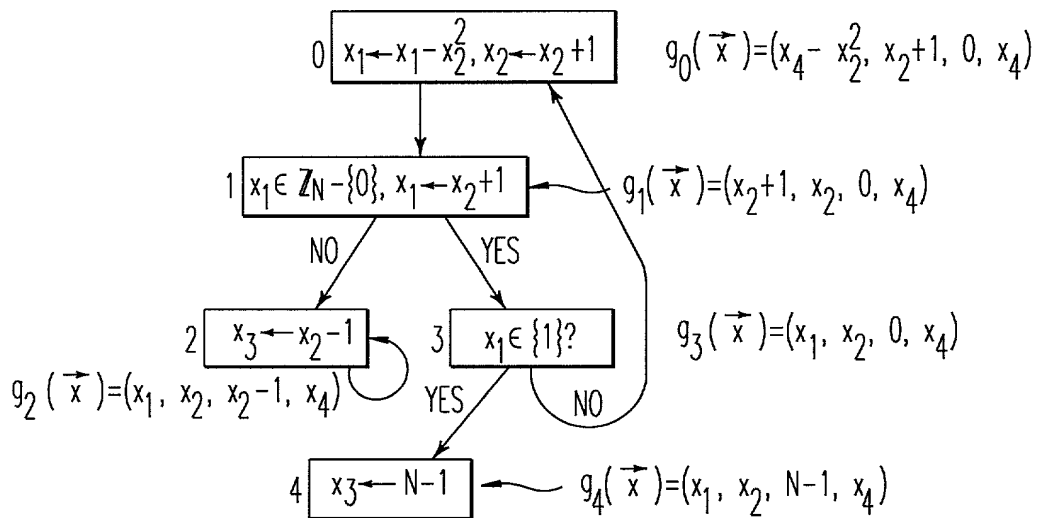


FIG. 20B



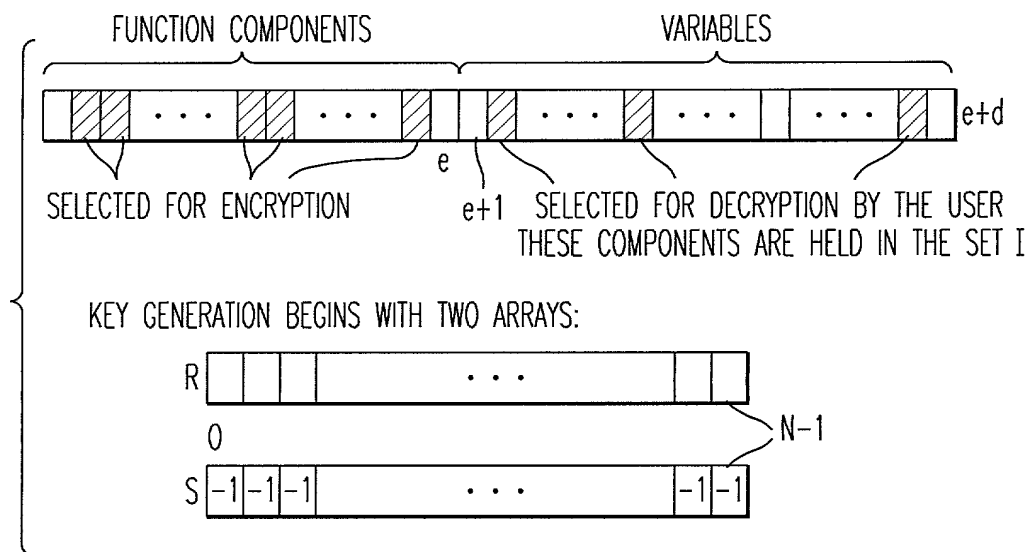


FIG. 22A

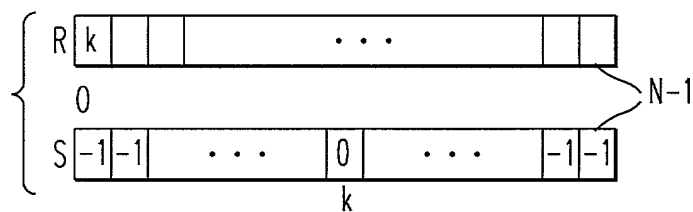


FIG. 22B

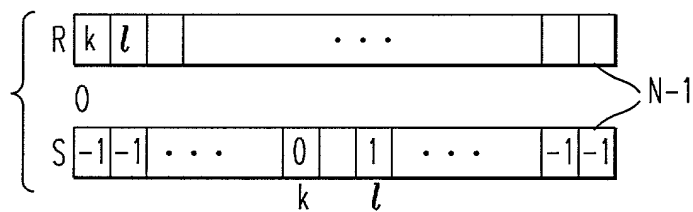


FIG. 22C

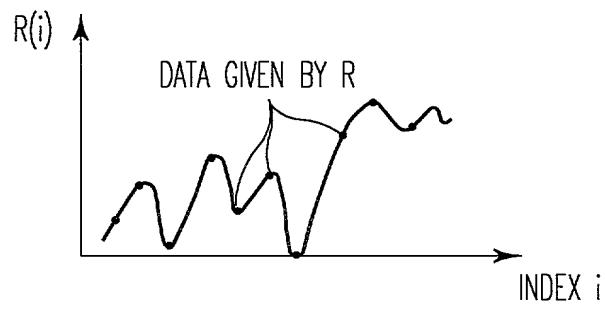


FIG. 23

X Y MOD 5					
X \ Y	0	1	2	3	4
0	0	0	0	0	0
1	0	1	2	3	4
2	0	2	4	1	3
3	0	3	1	4	2
4	0	4	3	2	1

FIG. 24A

$X^Y \text{ MOD } 5$					
X \ Y	0	1	2	3	4
0	1	0	0	0	0
1	1	1	1	1	1
2	1	2	4	3	1
3	1	3	4	2	1
4	1	4	1	4	1

FIG. 24B

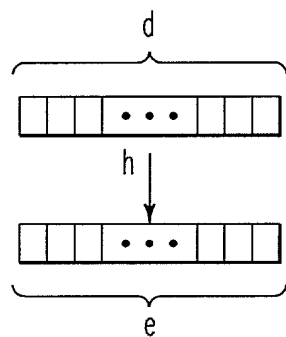


FIG. 25A

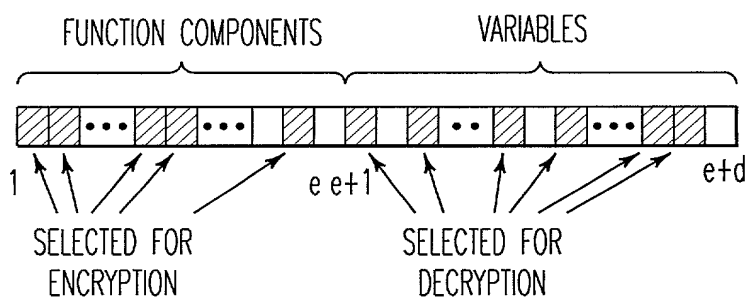


FIG. 25B

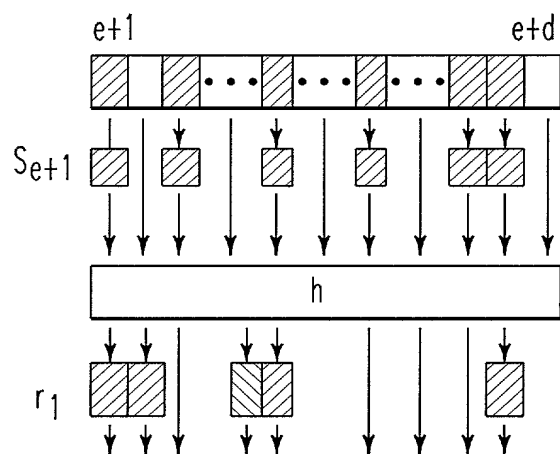


FIG. 25C

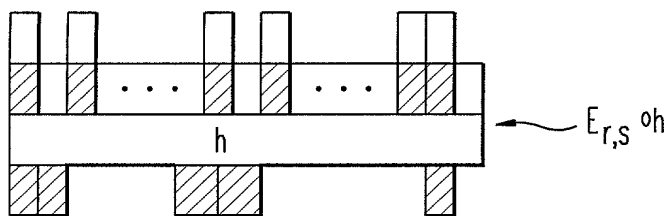


FIG. 26A

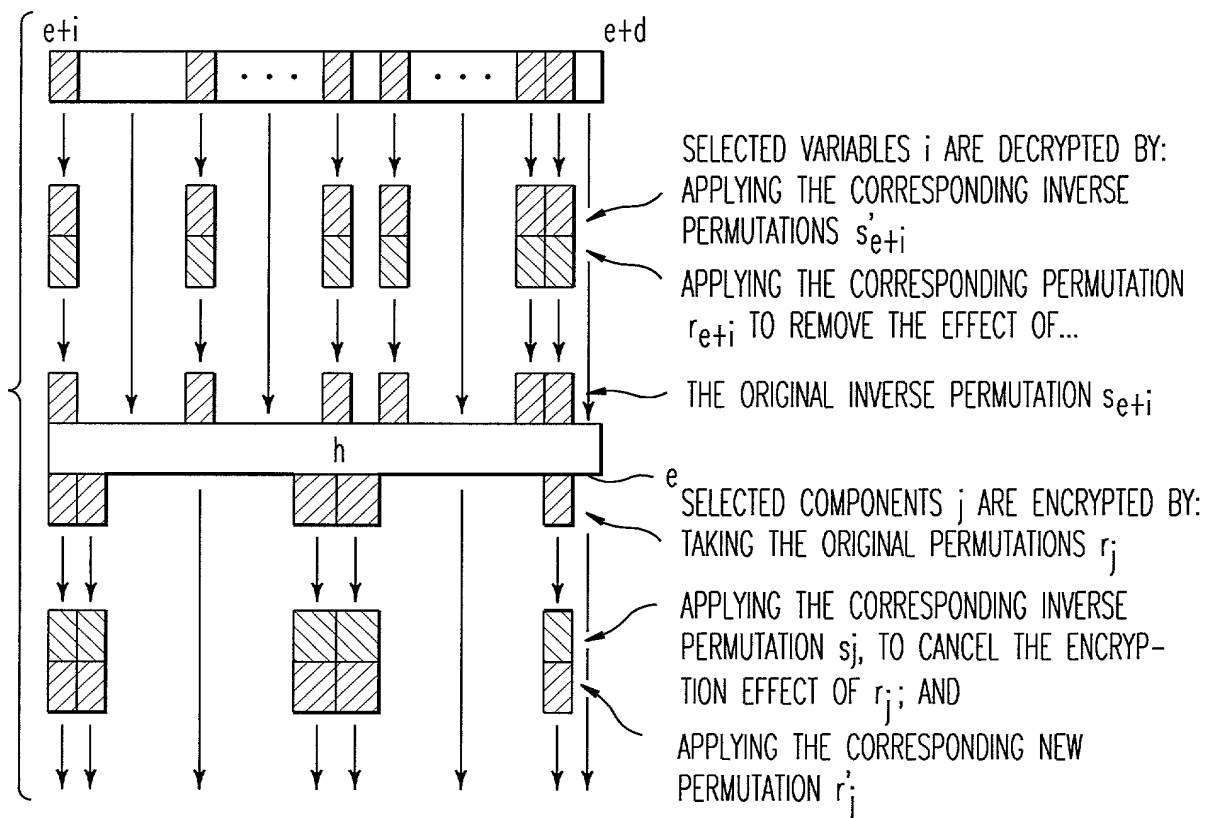


FIG. 26B

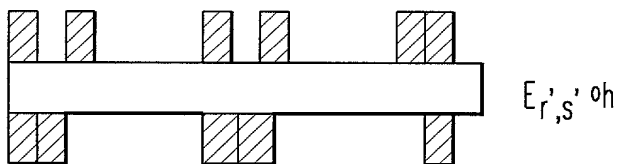


FIG. 26C

X ₂ \ X ₁	0	1	2	3	4
0	(3,4)	(1,2)	(4,0)	(2,1)	(1,3)
1	(0,0)	(2,3)	(3,4)	(4,1)	(0,2)
2	(2,0)	(3,2)	(1,2)	(0,1)	(1,4)
3	(4,0)	(2,0)	(4,4)	(4,4)	(2,4)
4	(1,1)	(2,2)	(1,0)	(4,1)	(4,2)

FIG. 27A

X	0	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
t _f	(2,3)	2	4	6	11	17	(1,3)	2	12	4	23	11	24	1	7	9	5	24	9	16	10	21	22	14

FIG. 27B

FUNCTION TABLE FOR f

1	2	3	4	5
---	---	---	---	---

FUNCTION TABLE FOR t_f

1	2	3	4	5
---	---	---	---	---

FIG. 27C

FIG. 27D

$x_1 \backslash x_2$	0	1	2	3	4
0	0	1	3	2	0
1	2	2	4	2	0
2	1	0	4	2	1
3	2	3	3	2	1
4	2	0	1	1	2

FIG. 28A

X	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
tf	23	0	2	4	6	11	17	13	2	12	4	23	11	24	1	7	9	5	24	9	16	10	21	22	14

FIG. 28B

X	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	13	16	17	18	19	20	21	22	23	24
tg	0	2	1	2	2	1	2	0	3	0	3	4	4	3	1	2	2	2	2	1	0	0	1	1	2

FIG. 28C

X	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
tgf	1	0	1	2	2	4	2	3	1	4	2	1	4	2	2	0	0	1	2	0	2	3	0	1	1

FIG. 28D

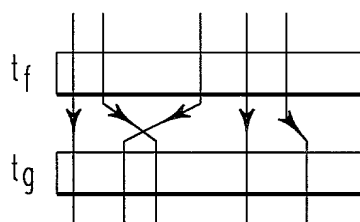


FIG. 28E

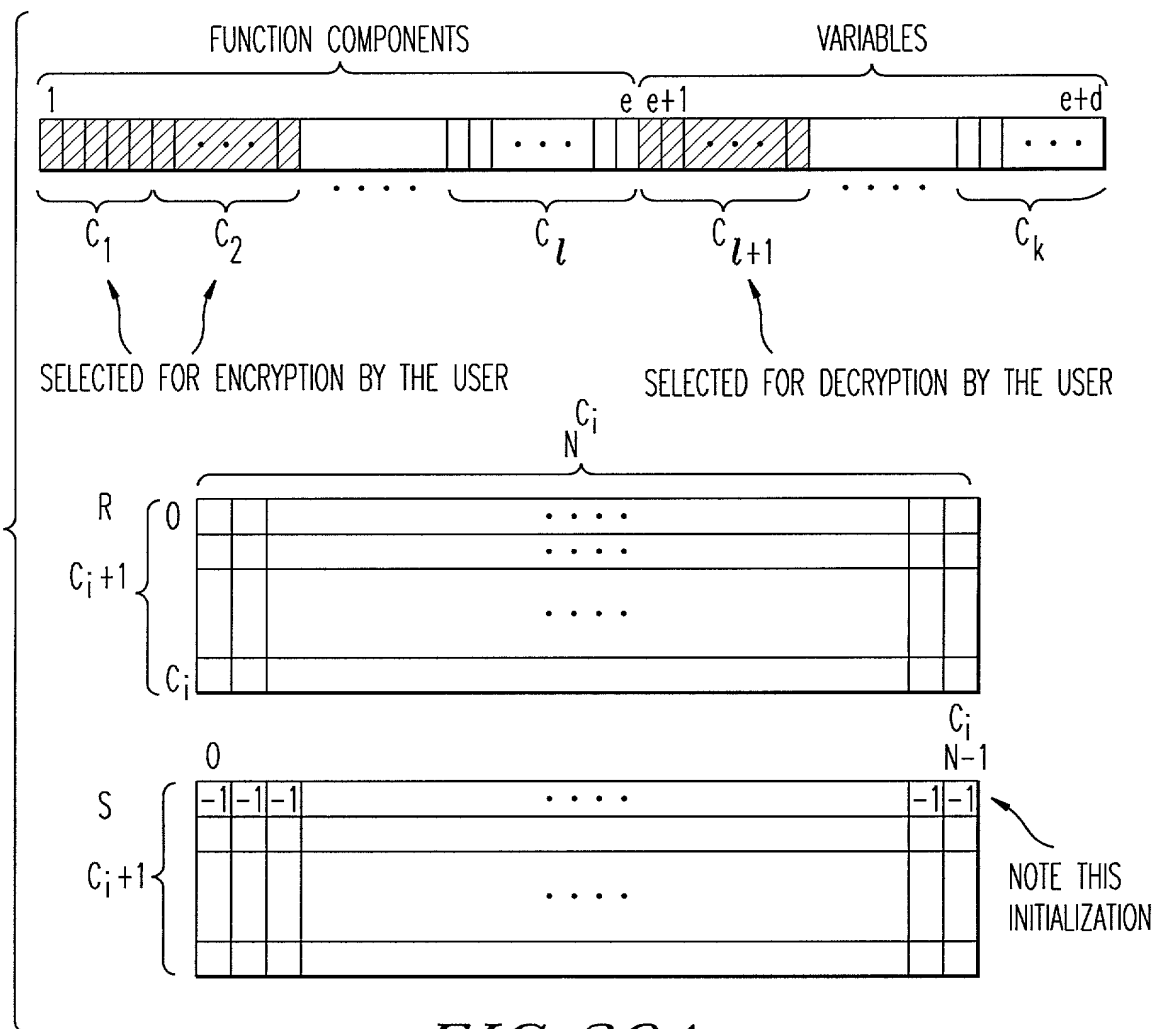


FIG. 29A

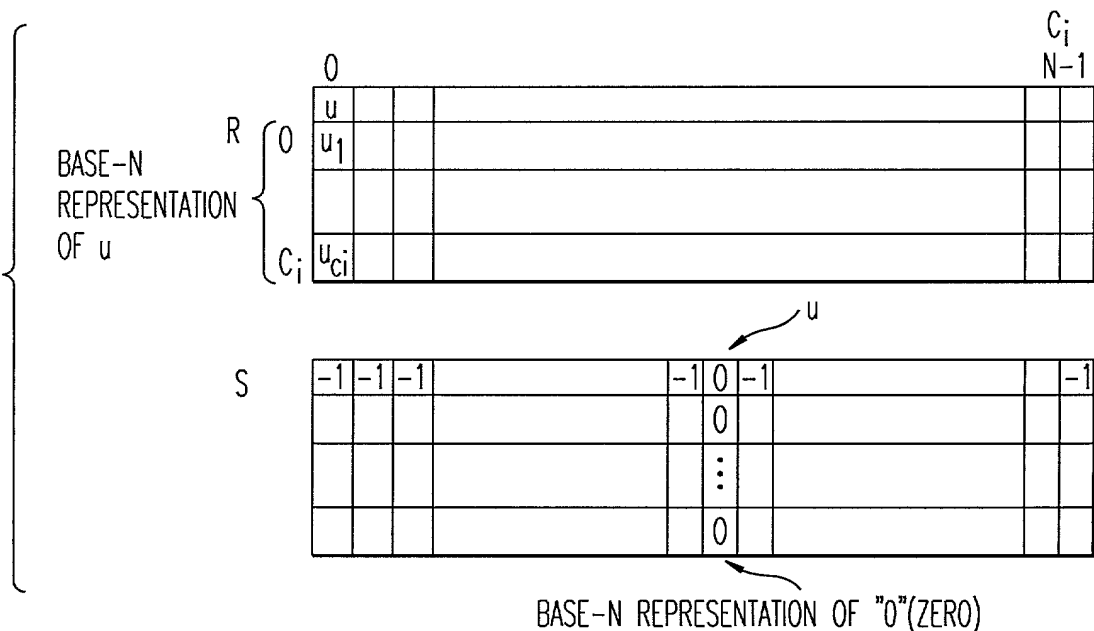
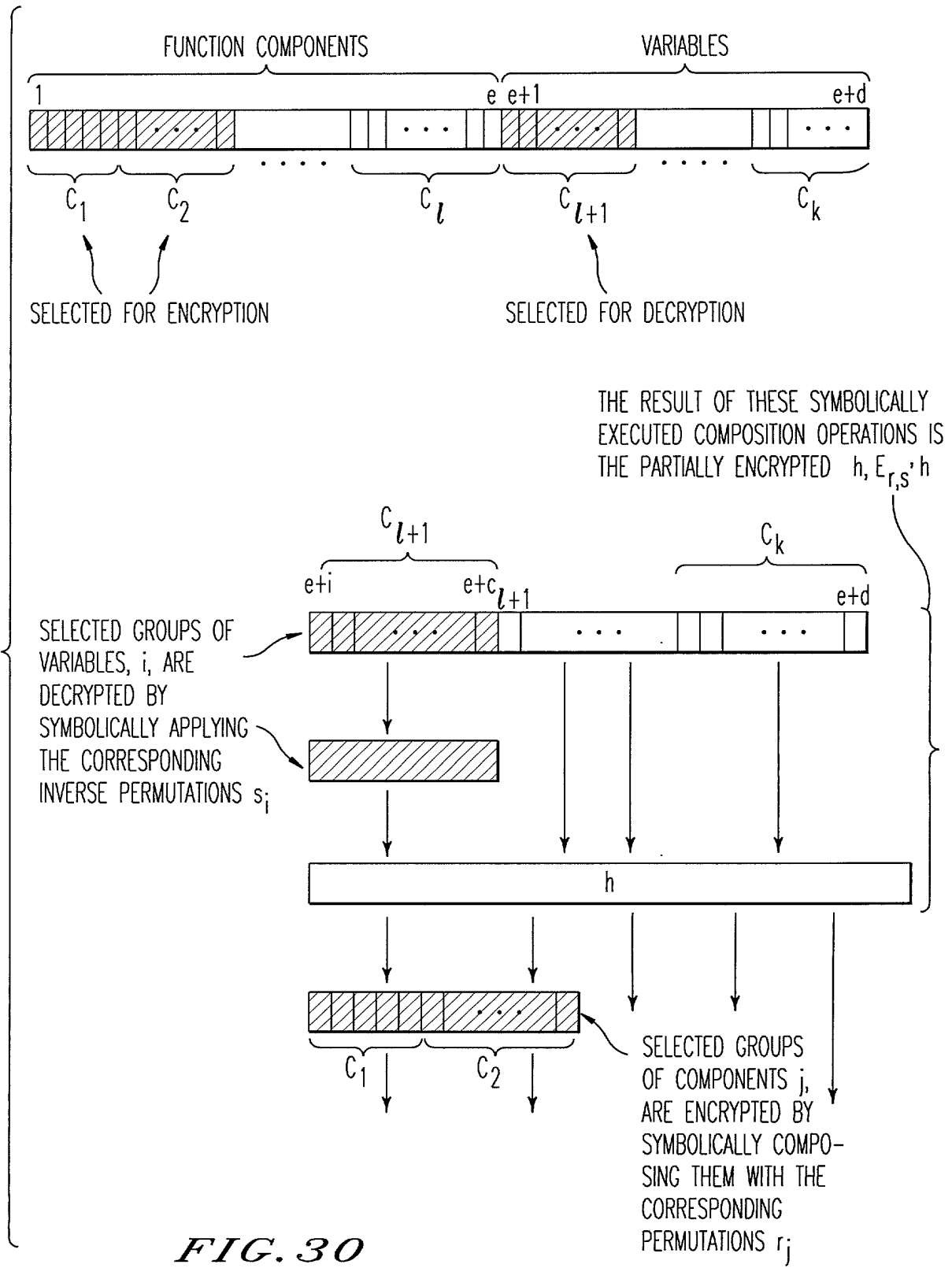


FIG. 29B



00872742 121300

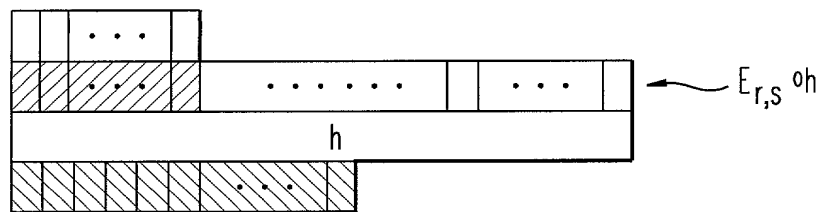


FIG. 31A c

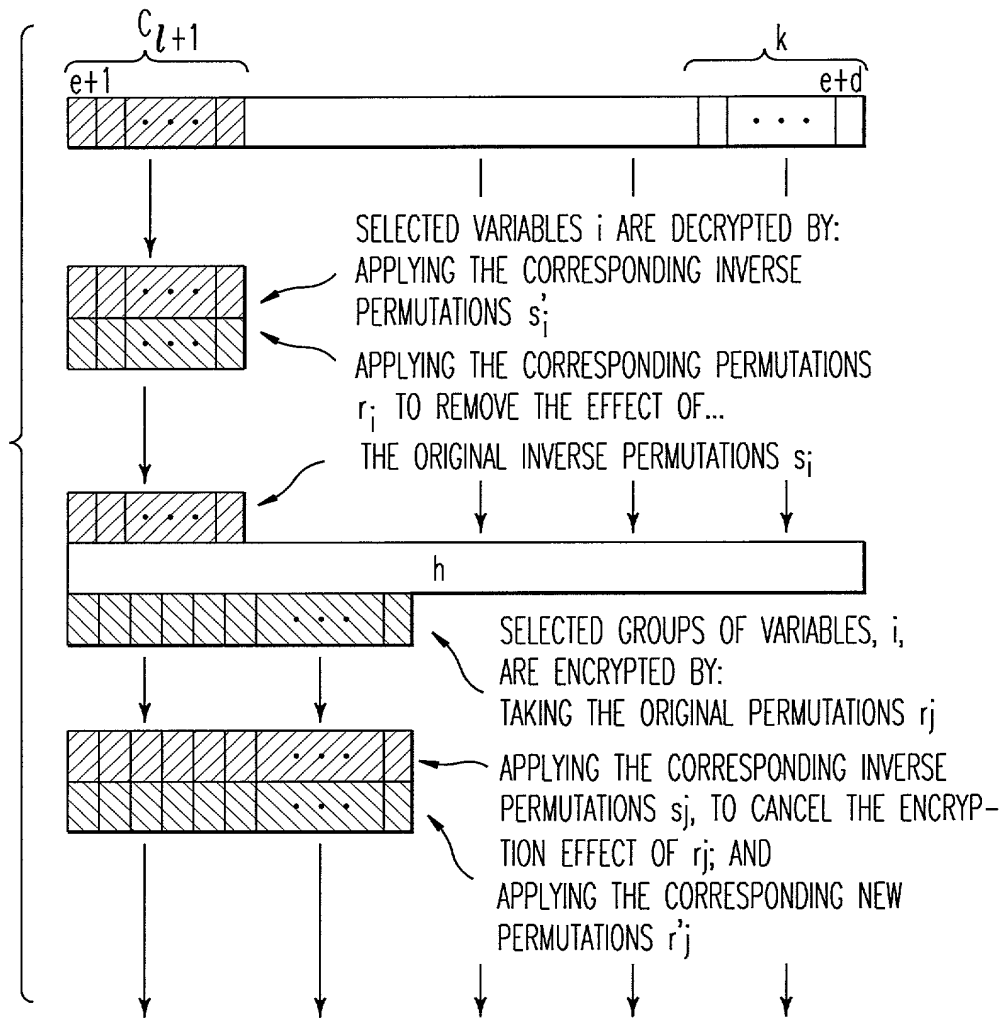


FIG. 31B

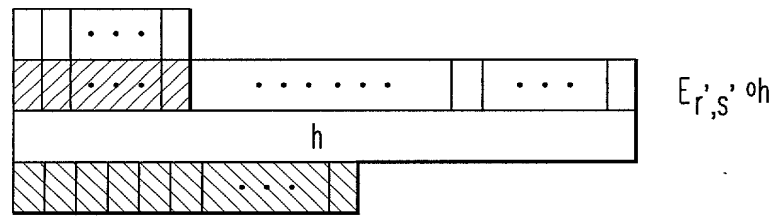
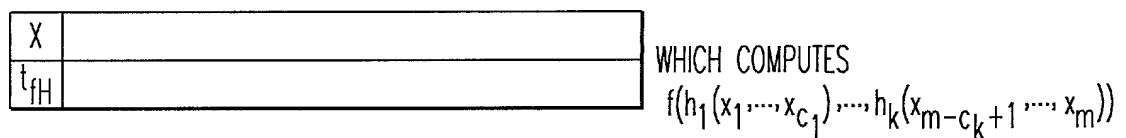
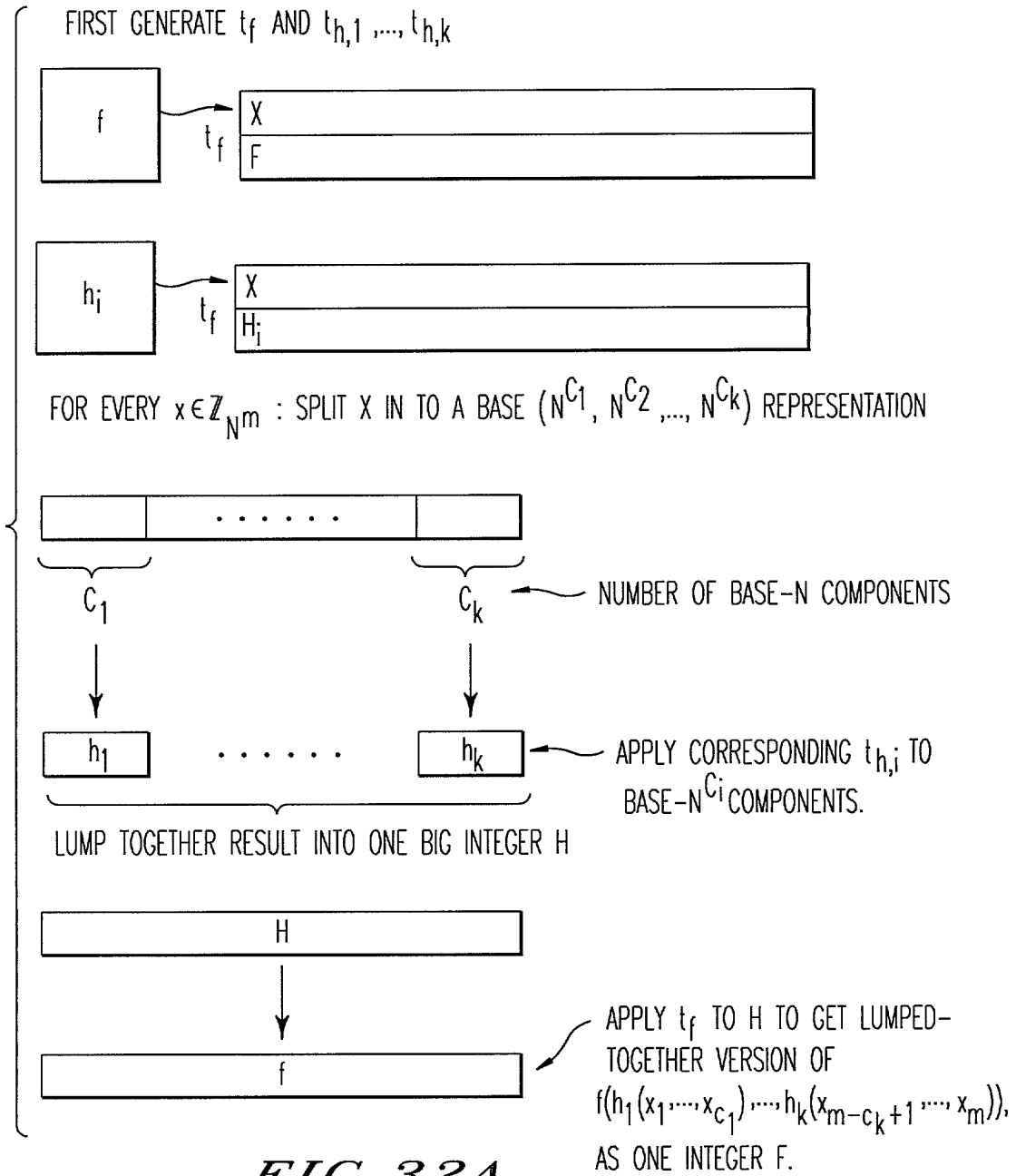


FIG. 31C



FIRST GENERATE t_f AND $t_{h,1}, \dots, t_{h,K}$

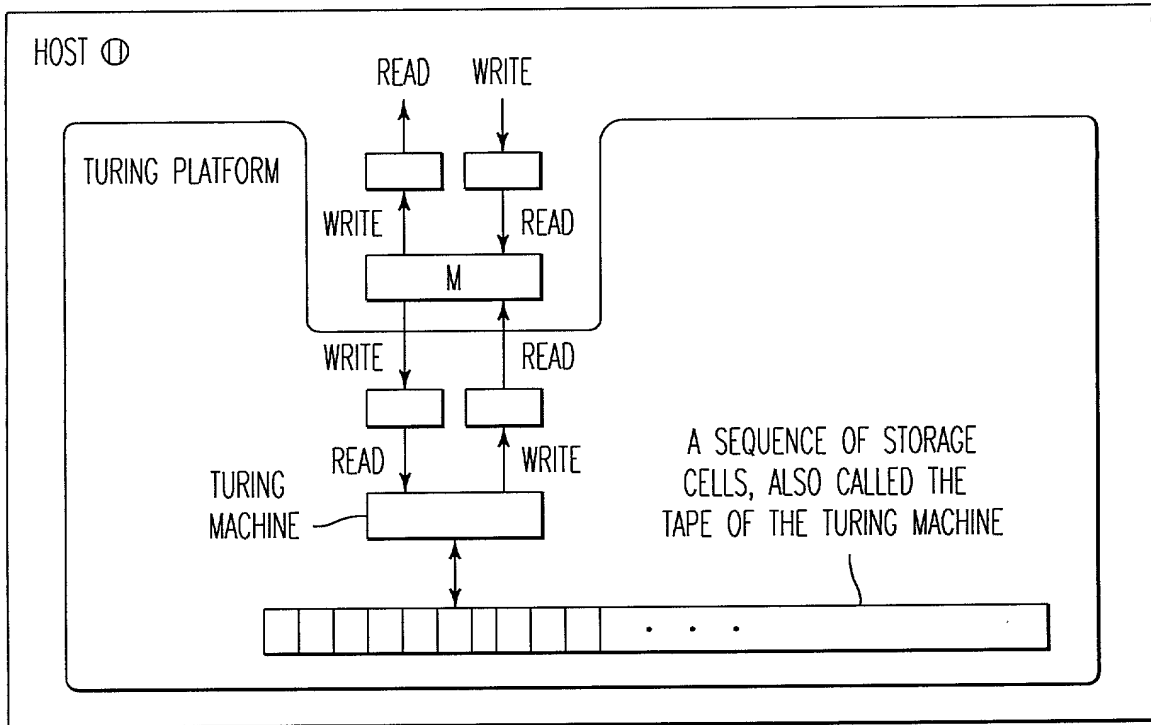


FIG. 34

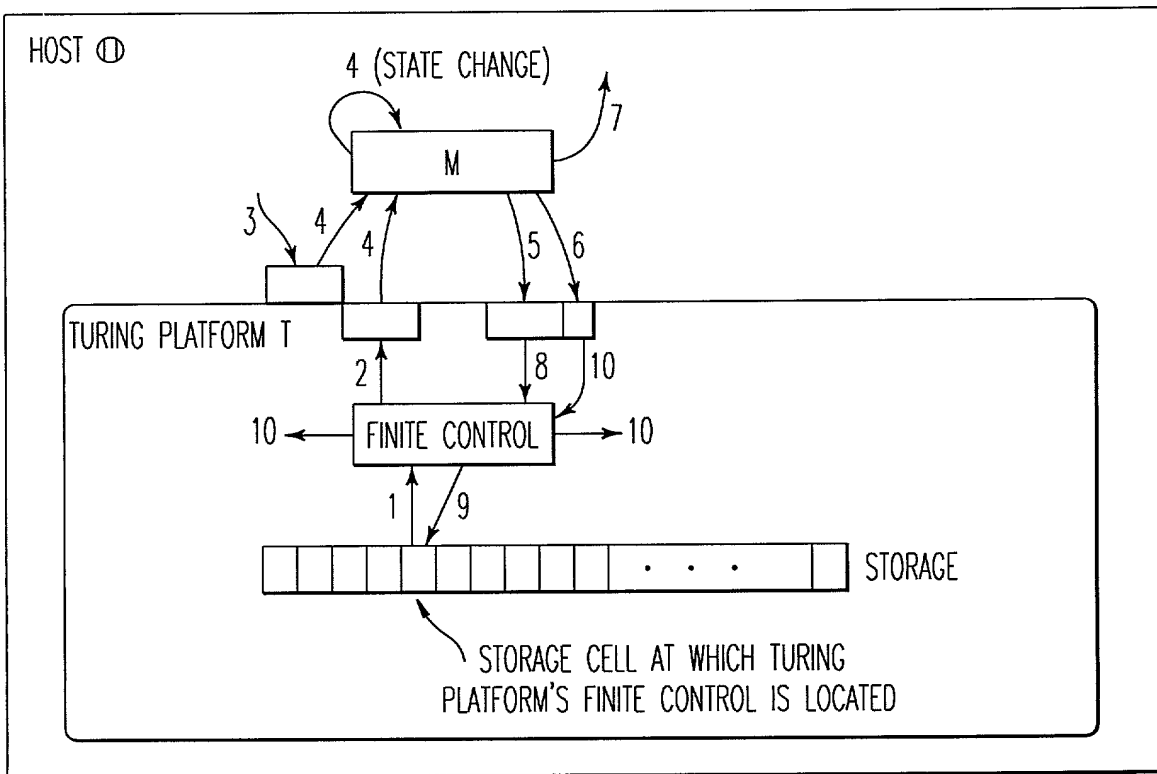


FIG. 35

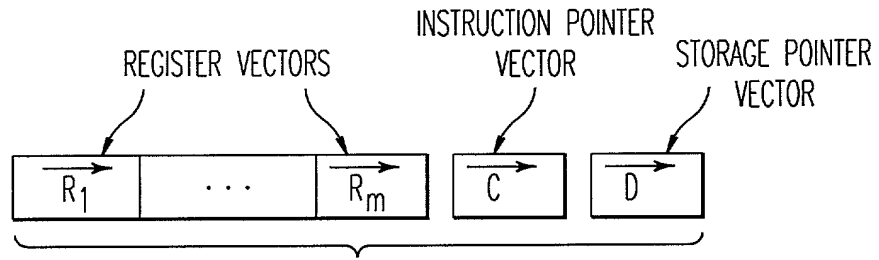


FIG. 36A

SHARED DATA IN THE
FORM OF D-VECTORS

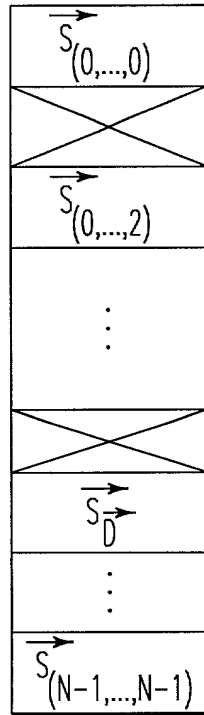


FIG. 36B

SET OF INSTRUCTIONS
P

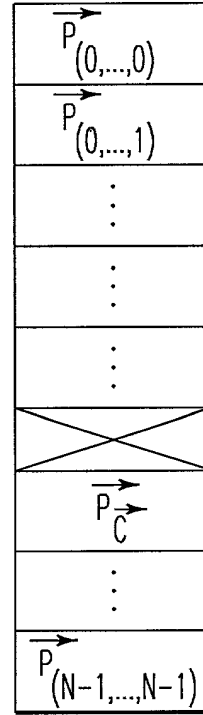


FIG. 36C

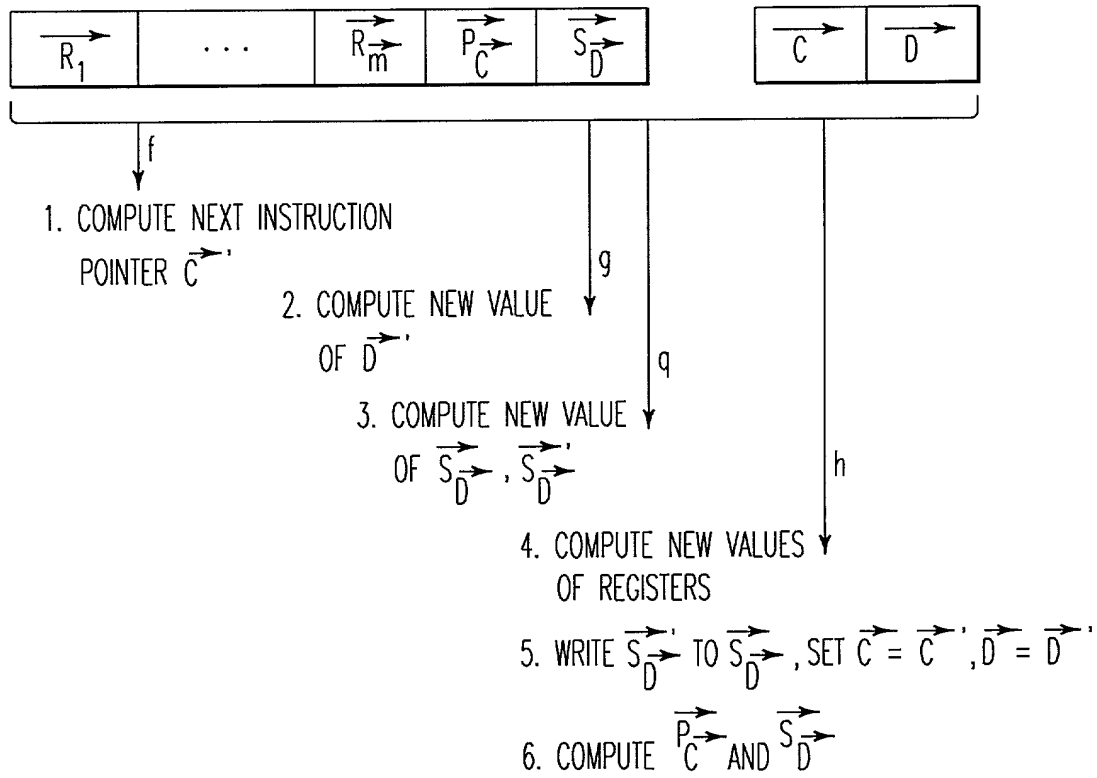


FIG. 36D

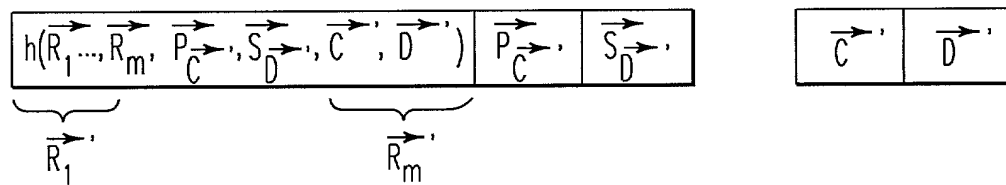


FIG. 36E

$$h_1: \mathbb{Z}_2^2 \rightarrow \mathbb{Z}_2^2$$

\vec{x}	$h(\vec{x})$
(0,0)	(1,0)
(0,1)	(1,1)
(1,0)	(0,0)
(1,1)	(0,1)

2. COMPONENT

1. COMPONENT

$$h_2: \mathbb{Z}_2^2 \rightarrow \mathbb{Z}_2^2$$

\vec{x}	$h(\vec{x})$
(0,0)	(1,1)
(0,1)	(0,0)
(1,0)	(1,0)
(1,1)	(1,0)

FIG. 37A

$$f: \mathbb{Z}_2^4 \rightarrow \mathbb{Z}_2^3$$

\vec{x}	$f(\vec{x})$
(0,0,0,0)	(1,0,1)
(0,0,0,1)	(0,0,1)
(0,0,1,0)	(1,0,1)
(0,0,1,1)	(0,0,0)
(0,1,0,0)	(1,0,0)
(0,1,0,1)	(0,0,0)
(0,1,1,0)	(1,1,1)
(0,1,1,1)	(1,0,0)
(1,0,0,0)	(1,1,0)
(1,0,0,1)	(0,0,1)
(1,0,1,0)	(0,1,1)
(1,0,1,1)	(1,0,1)
(1,1,0,0)	(1,1,1)
(1,1,0,1)	(0,0,0)
(1,1,1,0)	(1,1,0)
(1,1,1,1)	(0,1,0)

FIG. 37B

$$g: \mathbb{Z}_2^3 \rightarrow \mathbb{Z}_2^3$$

\vec{x}	$g(\vec{x})$
(0,0,0)	(1,0,1)
(0,0,1)	(0,0,0)
(0,1,0)	(1,1,1)
(0,1,1)	(1,0,0)
(1,0,0)	(0,1,1)
(1,0,1)	(1,0,1)
(1,1,0)	(1,1,0)
(1,1,1)	(1,1,1)

FIG. 37C

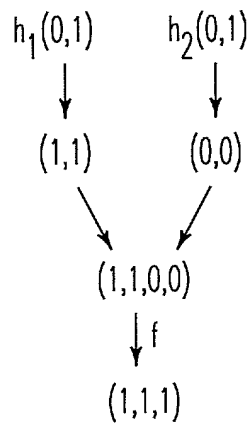


FIG. 37D

$$f: \mathbb{Z}_2^4 \rightarrow \mathbb{Z}_2^3$$

\vec{x}	$f(\vec{x})$
(0,0,0,0)	(1,0,1)
(0,0,0,1)	(0,0,1)
(0,0,1,0)	(1,0,1)
(0,0,1,1)	(0,0,0)
(0,1,0,0)	(1,0,0)
(0,1,0,1)	(0,0,0)
(0,1,1,0)	(1,1,1)
(0,1,1,1)	(1,0,0)
(1,0,0,0)	(1,1,0)
(1,0,0,1)	(0,0,1)
(1,0,1,0)	(0,1,1)
(1,0,1,1)	(1,0,1)
(1,1,0,0)	(1,1,1)
(1,1,0,1)	(0,0,0)
(1,1,1,0)	(1,1,0)
(1,1,1,1)	(0,1,0)

FIG. 38A

$$h_1: \mathbb{Z}_2^2 \rightarrow \mathbb{Z}_2^2$$

\vec{x}	$h_1(\vec{x})$
(0,0)	(1,0)
(0,1)	(1,1)
(1,0)	(0,0)
(1,1)	(0,1)

$$h_2: \mathbb{Z}_2^2 \rightarrow \mathbb{Z}_2^2$$

\vec{x}	$h_2(\vec{x})$
(0,0)	(1,1)
(0,1)	(0,0)
(1,0)	(1,0)
(1,1)	(1,0)

FIG. 38B

$$g: \mathbb{Z}_2^4 \rightarrow \mathbb{Z}_2^4$$

\vec{x}	$g(\vec{x})$
(0,0,0,0)	(0,0,0,0)
(0,0,0,1)	(1,1,0,0)
(0,0,1,0)	(0,1,0,0)
(0,0,1,1)	(1,0,1,1)
(0,1,0,0)	(0,0,1,0)
(0,1,0,1)	(1,0,1,1)
(0,1,1,0)	(0,1,1,0)
(0,1,1,1)	(0,0,1,1)
(1,0,0,0)	(0,0,1,0)
(1,0,0,1)	(1,1,0,0)
(1,0,1,0)	(1,1,1,0)
(1,0,1,1)	(0,1,0,0)
(1,1,0,0)	(0,1,1,0)
(1,1,0,1)	(1,0,1,1)
(1,1,1,0)	(0,0,1,0)
(1,1,1,1)	(1,0,1,0)

FIG. 38C

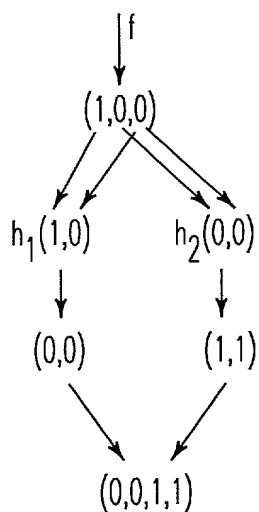


FIG. 38D

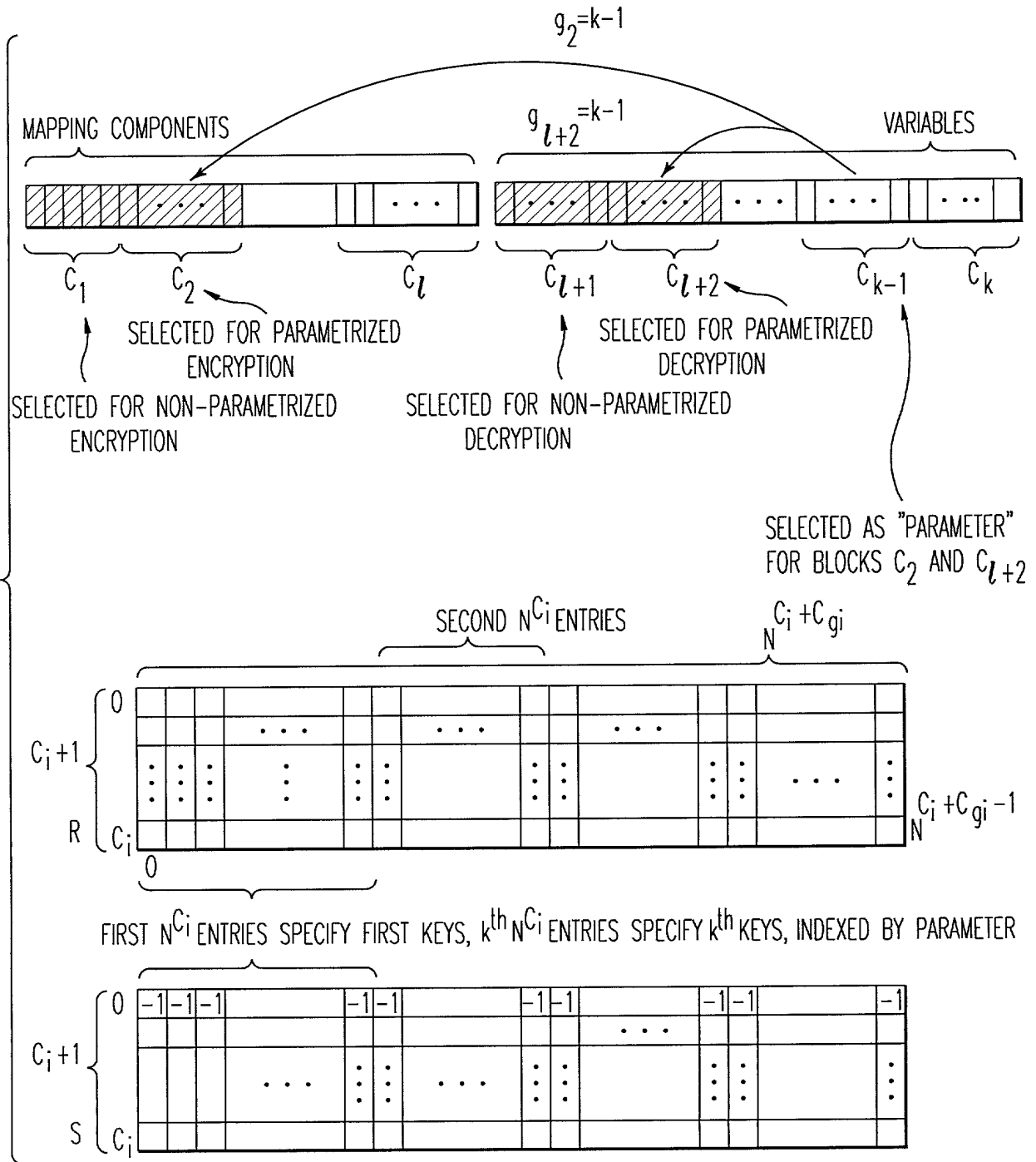
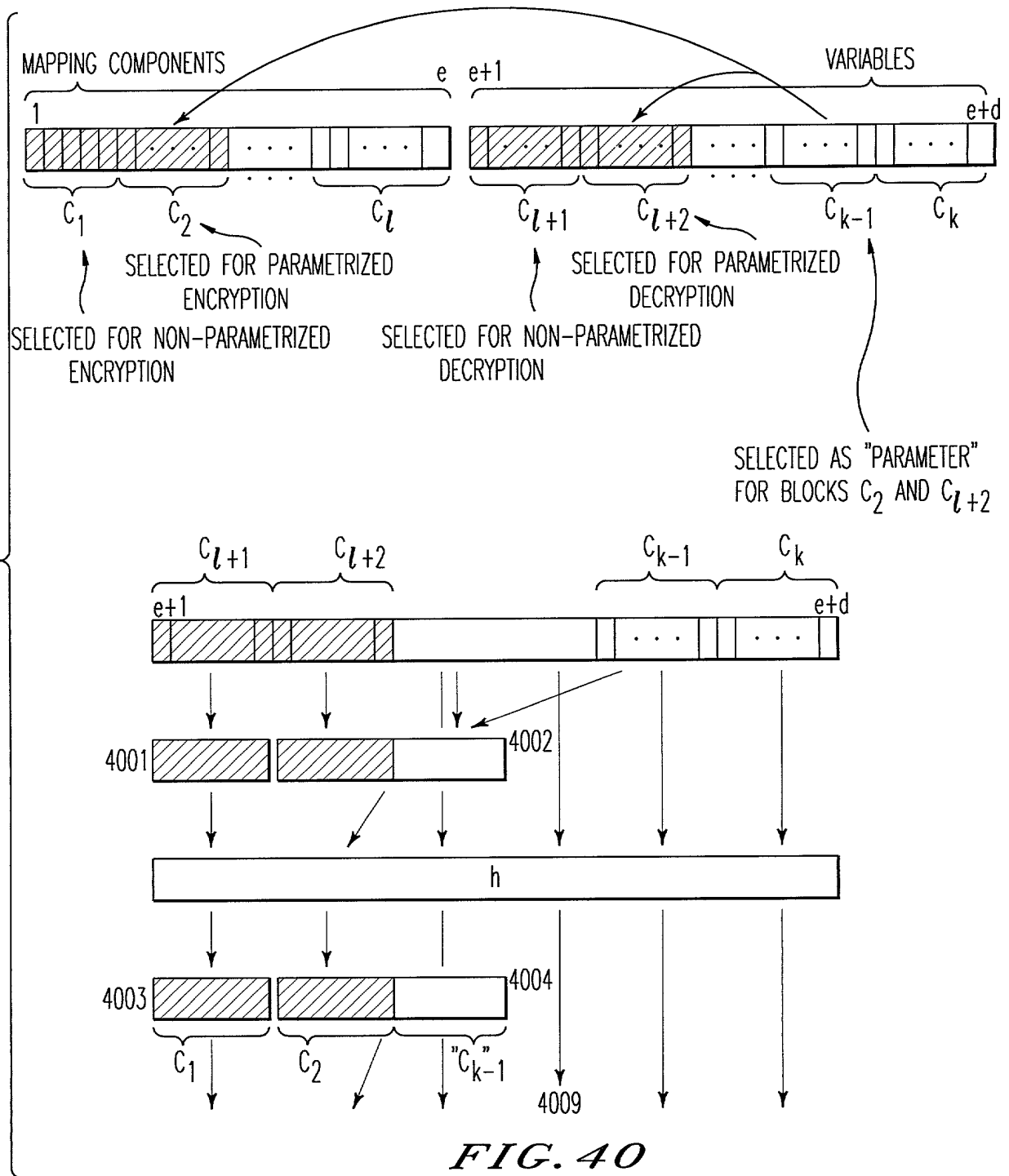
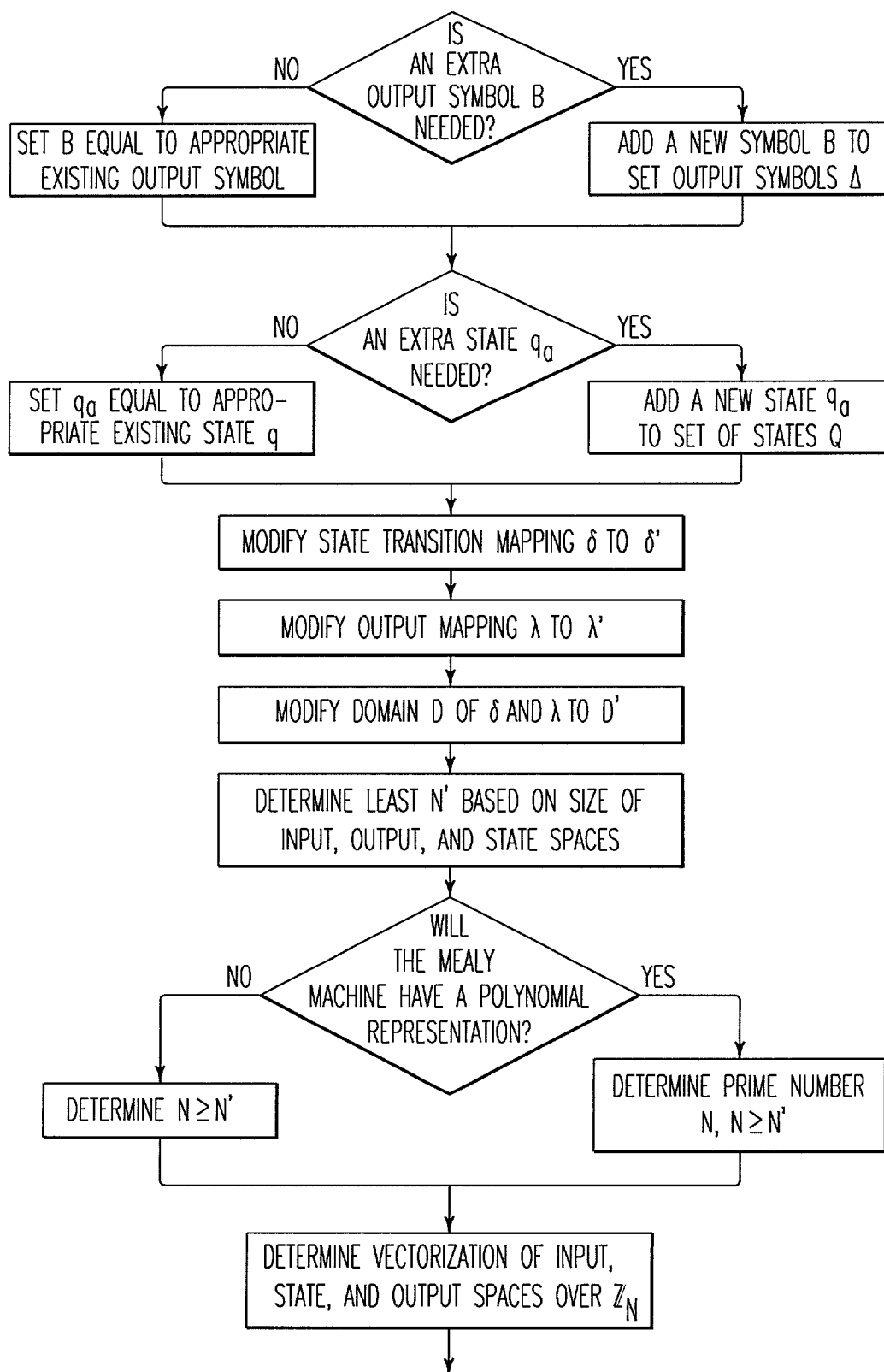


FIG. 39A





TO FIG. 41B

FIG. 41A

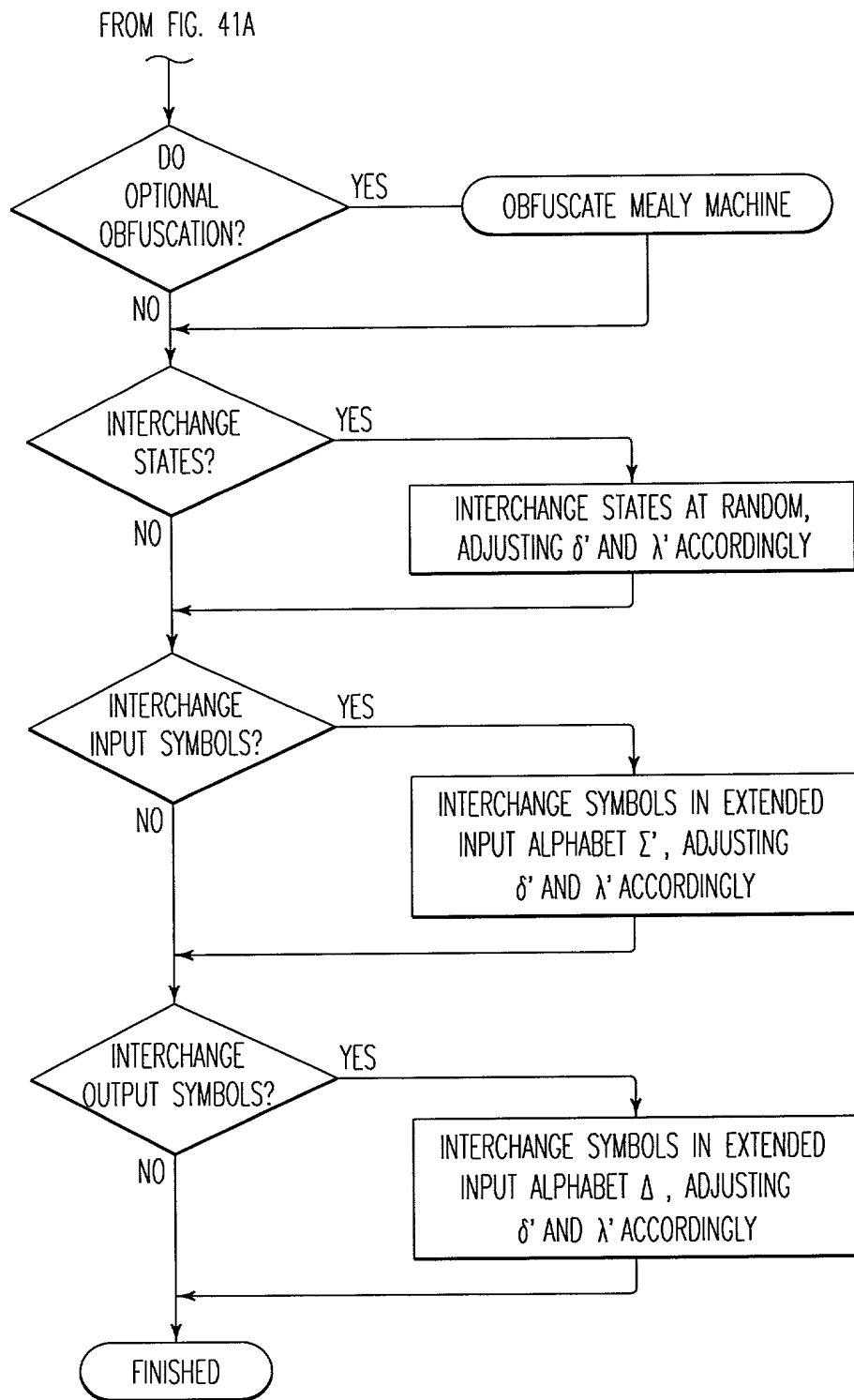


FIG. 41B

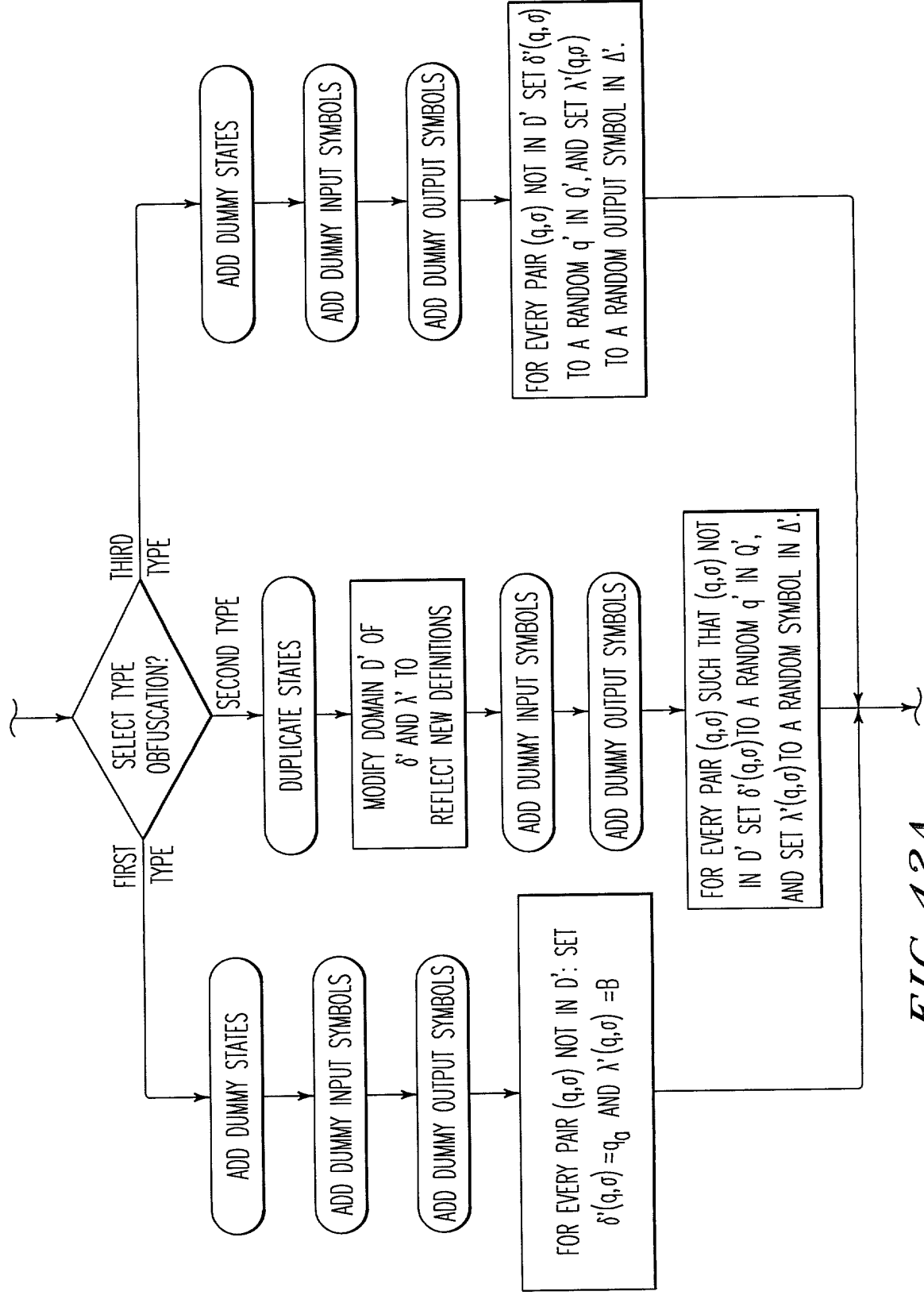


FIG. 42A

FIG. 42B

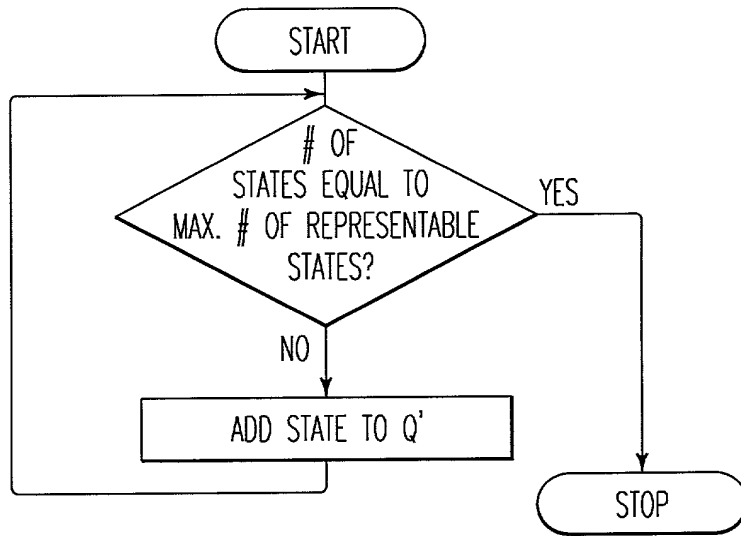


FIG. 42C

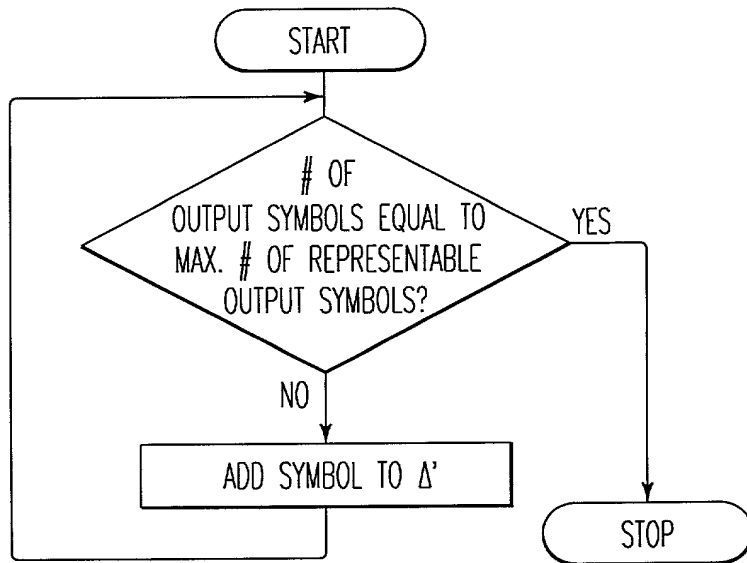
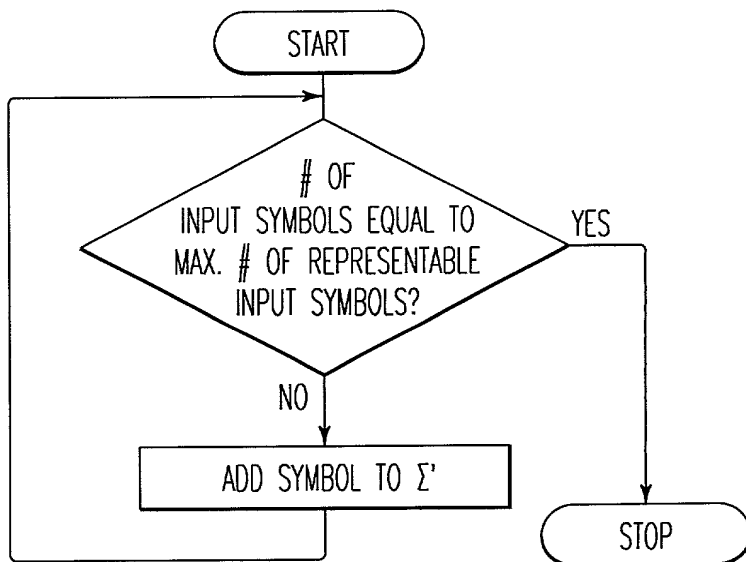


FIG. 42D



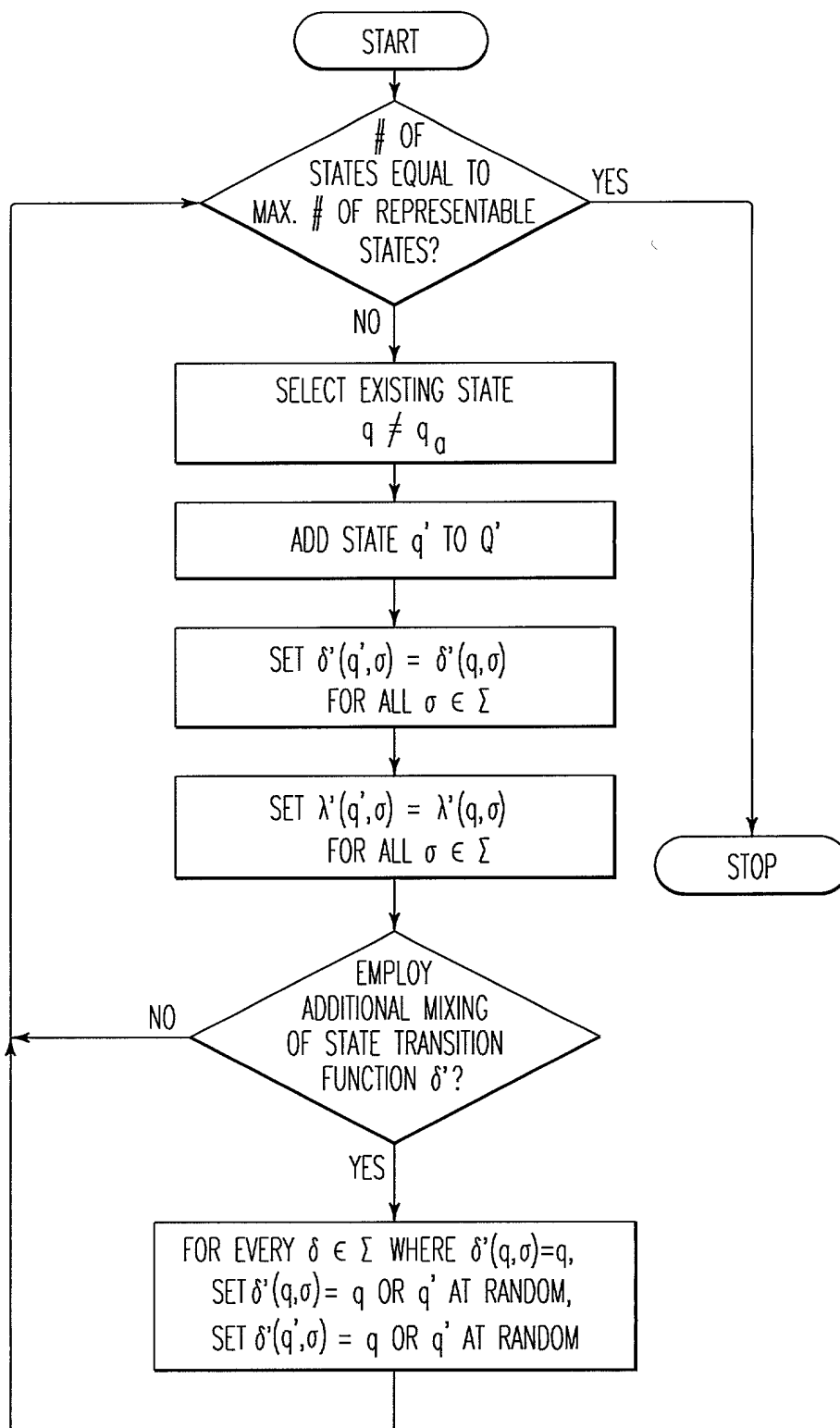


FIG. 42E

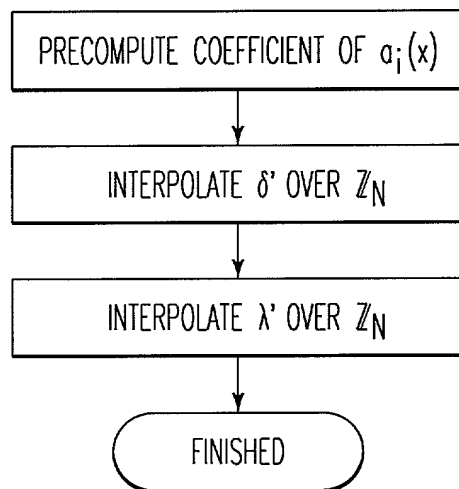


FIG. 43A

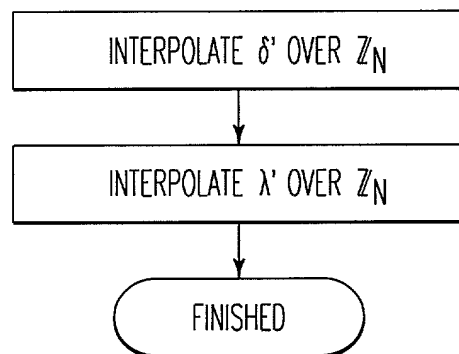
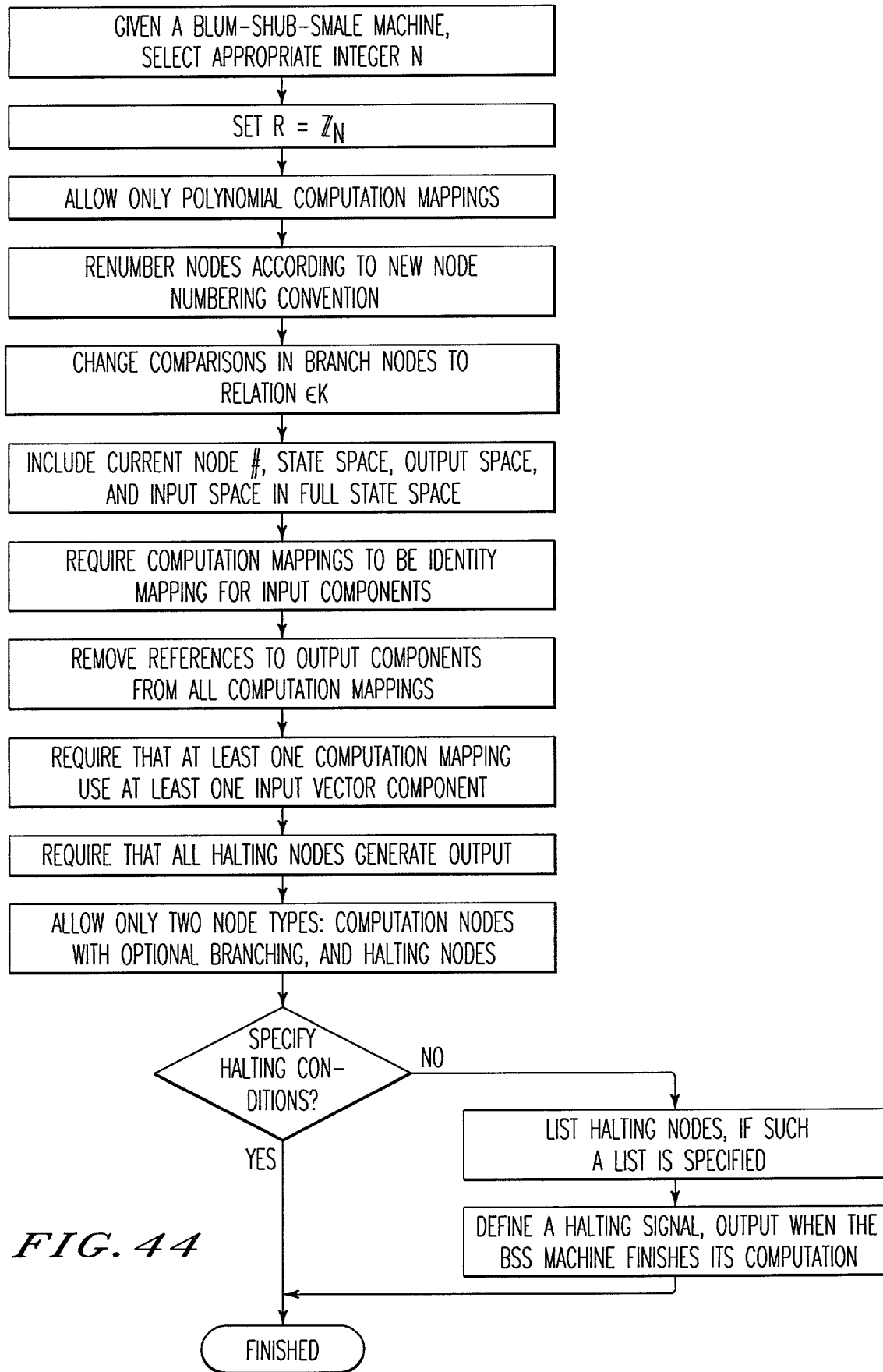


FIG. 43B



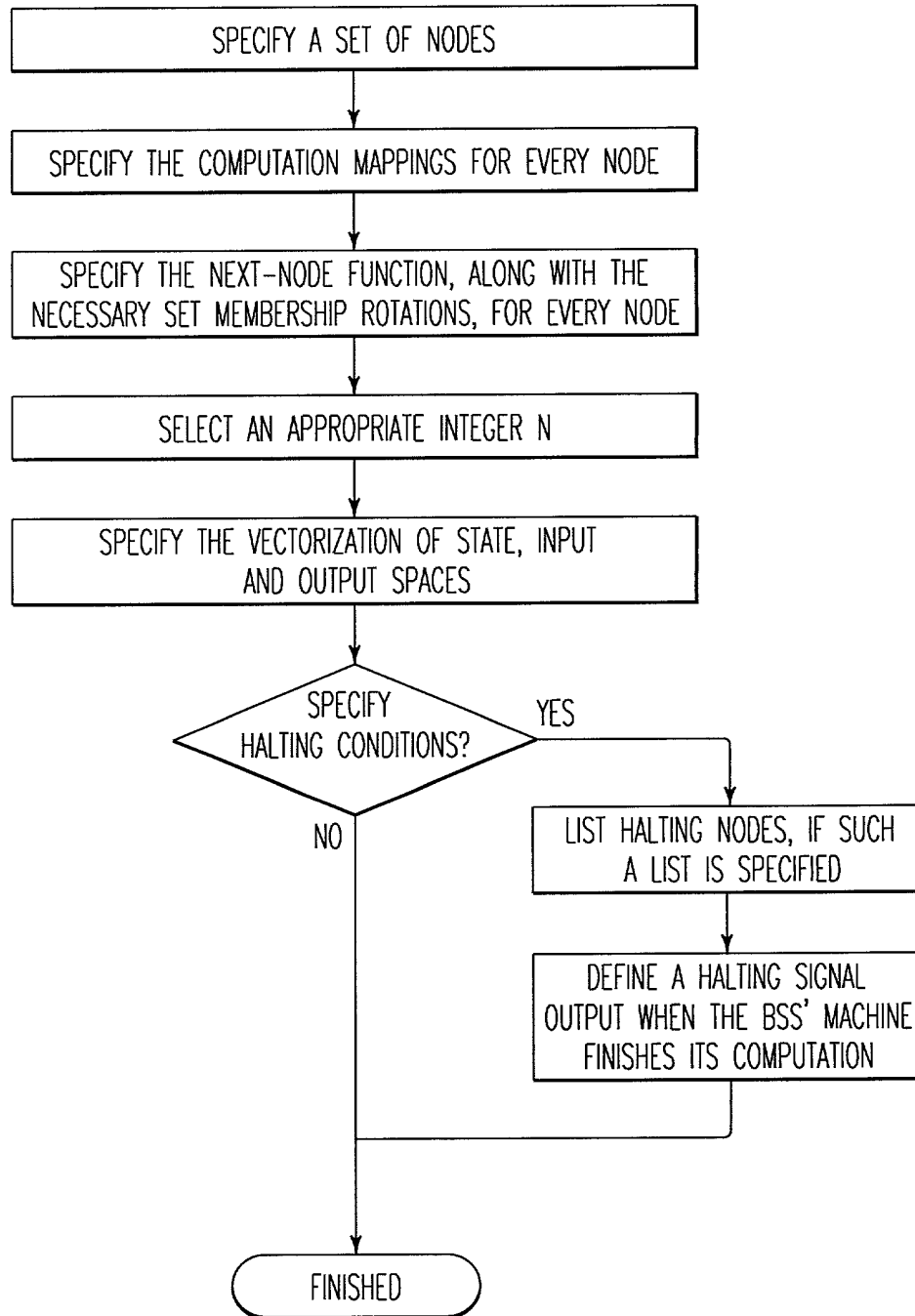


FIG. 45

```
graph TD; A[ACQUIRE A SPECIFICATION OF BSS' MACHINE] --> B[EXPRESS SET MEMBERSHIP RELATIONS,  $\epsilon K, K \in \mathbb{Z}_N - \{0\}$  AS POLYNOMIALS]; B --> C[EXPRESS THE NEXT-NODE FUNCTION  $\beta$  AS A POLYNOMIAL]; C --> D[EXPRESS THE ENTIRE COMPUTING ENDOMORPHISM  $H$  AS ONE MULTIVARIATE POLYNOMIAL MAPPING];
```

ACQUIRE A SPECIFICATION OF BSS' MACHINE

EXPRESS SET MEMBERSHIP RELATIONS,
 $\epsilon K, K \in \mathbb{Z}_N - \{0\}$ AS POLYNOMIALS

EXPRESS THE NEXT-NODE FUNCTION β AS A POLYNOMIAL

EXPRESS THE ENTIRE COMPUTING ENDOMORPHISM H AS
ONE MULTIVARIATE POLYNOMIAL MAPPING

FIG. 46

Figure 1. The effect of the concentration of the *Agrobacterium* strain on the transformation efficiency of *Agrobacterium* strain 102. The concentration of the *Agrobacterium* strain 102 was varied from 10⁵ to 10⁸ cells/ml. The transformation efficiency was determined by the number of transformants per 10⁵ cells of the *Agrobacterium* strain 102. The data are the mean \pm SD of three independent experiments. The asterisk (*) indicates a significant difference from the control (p < 0.05).

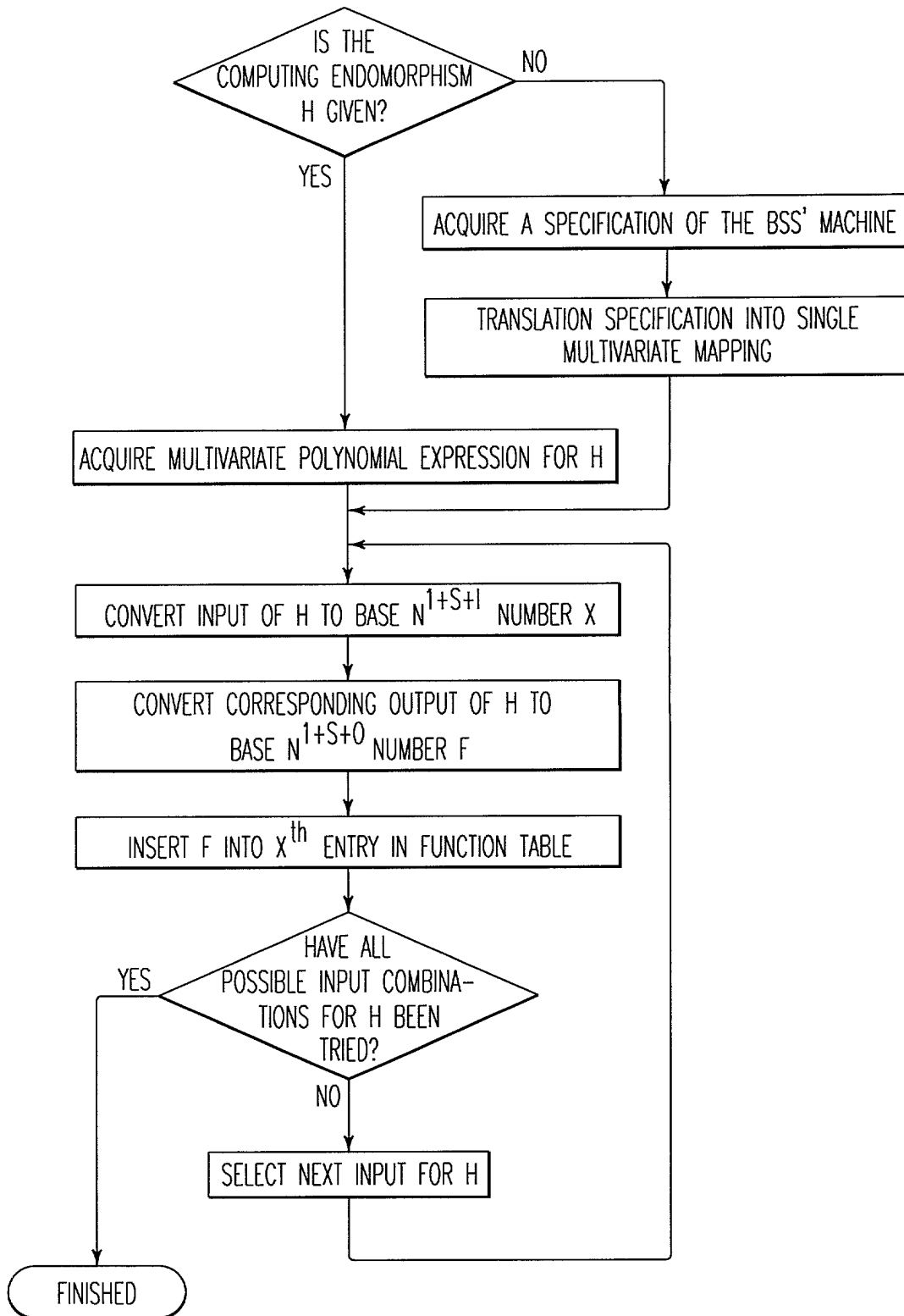


FIG. 47

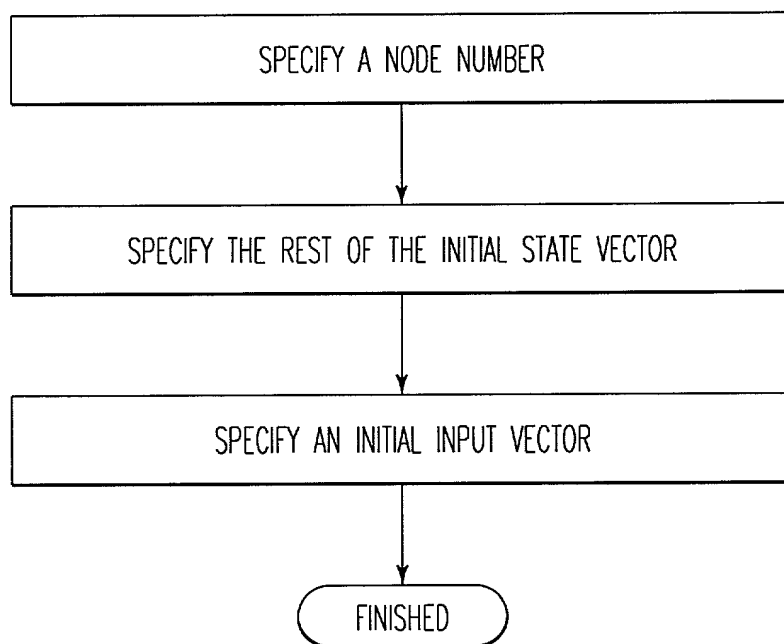


FIG. 48

```

graph TD
    A[INITIALIZE MACHINE WITH A SPECIFICATION FOR AN INITIAL STATE] --> B[DETERMINE HOW TO APPROPRIATELY EVALUATE H]
    B --> C[APPLY IT TO THE FULL STATE SPACE VECTOR]
    C --> D{READ OUTPUT?}
    D -- YES --> E[READ OUTPUT OF MACHINE]
    E --> D
    D -- NO --> F{CHANGE INPUT?}
    F -- YES --> G[CHANGE INPUT VECTOR]
    G --> F
    F -- NO --> H{HAS A HALTING CONDITION BEEN SATISFIED?}
    H -- YES --> I([FINISHED])
    H -- NO --> B

```

FINISHED

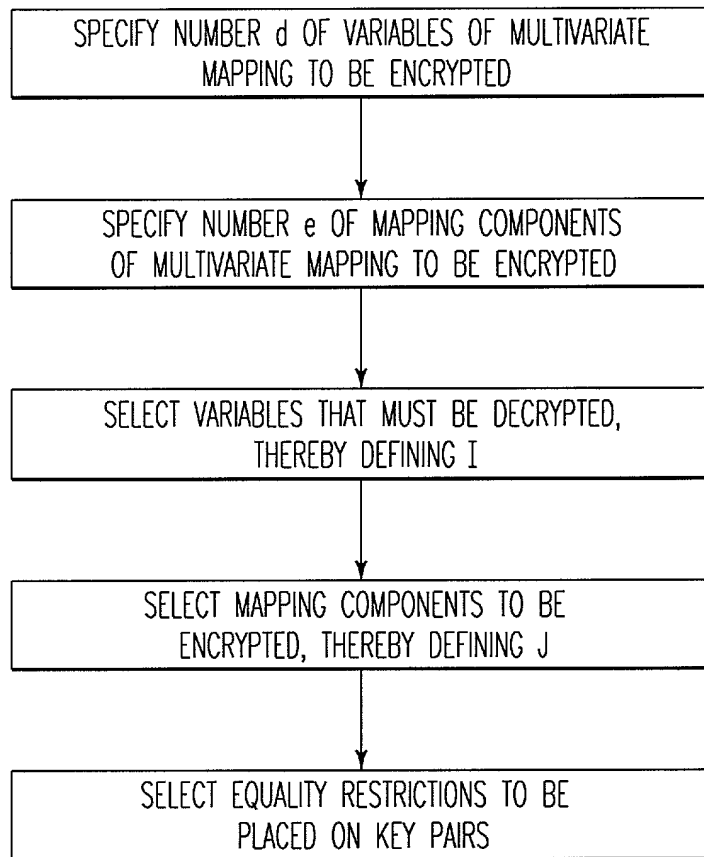


FIG. 50

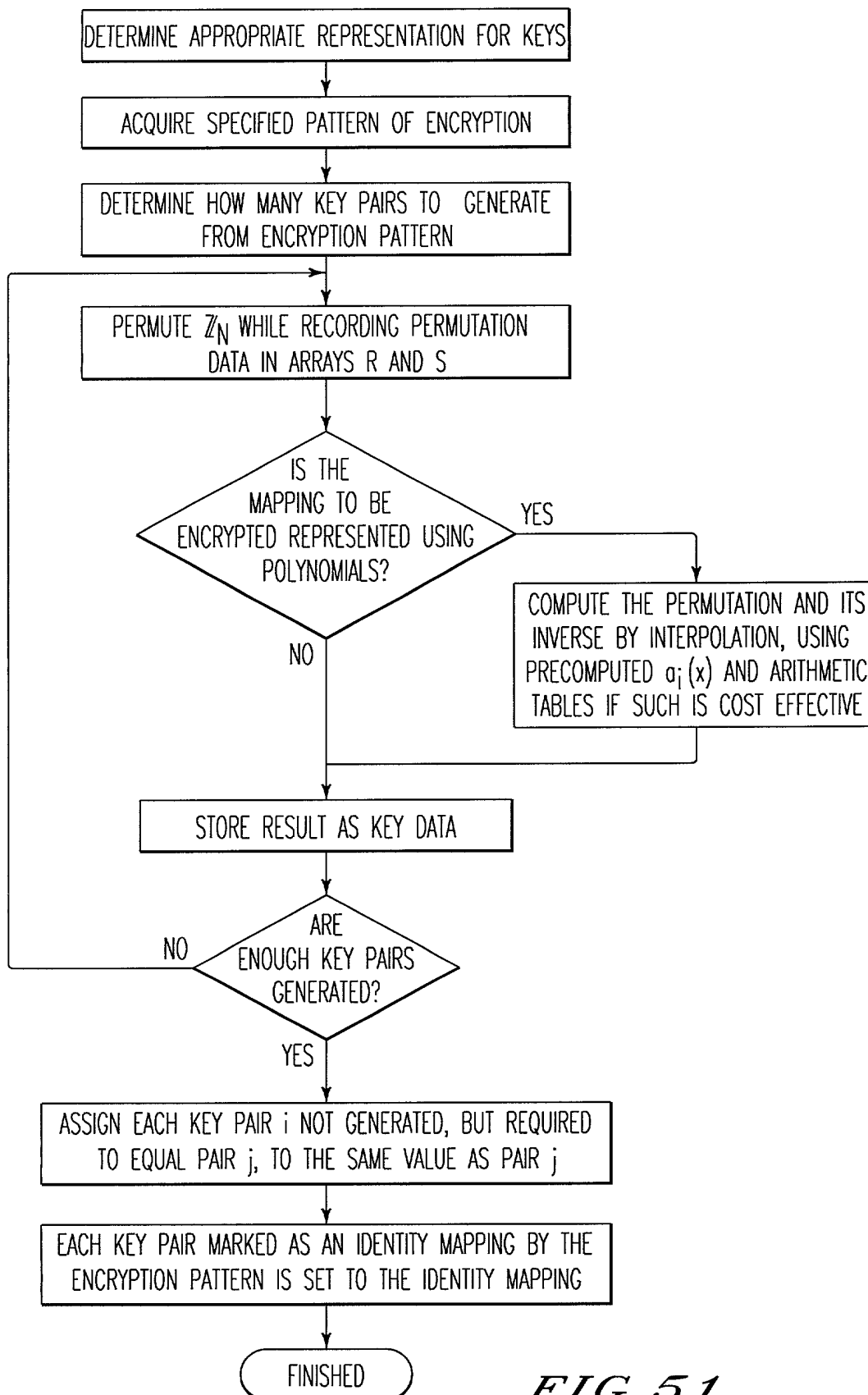


FIG. 51

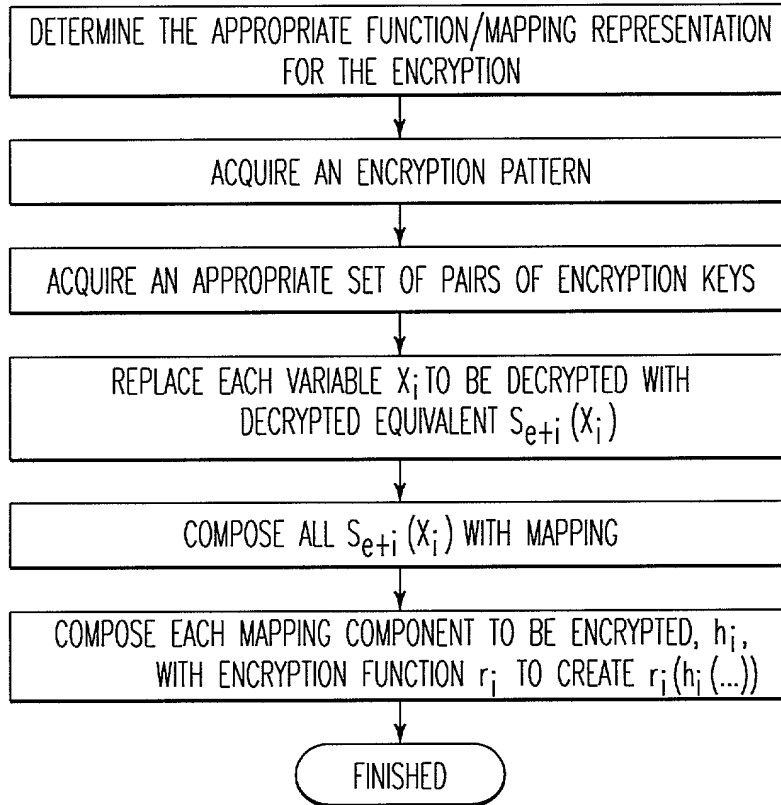


FIG. 52

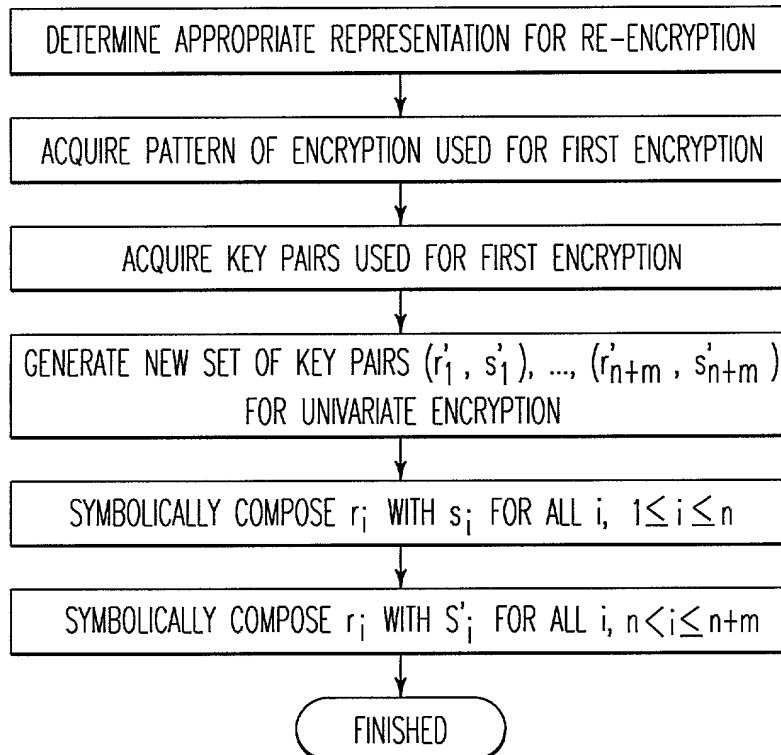


FIG. 53

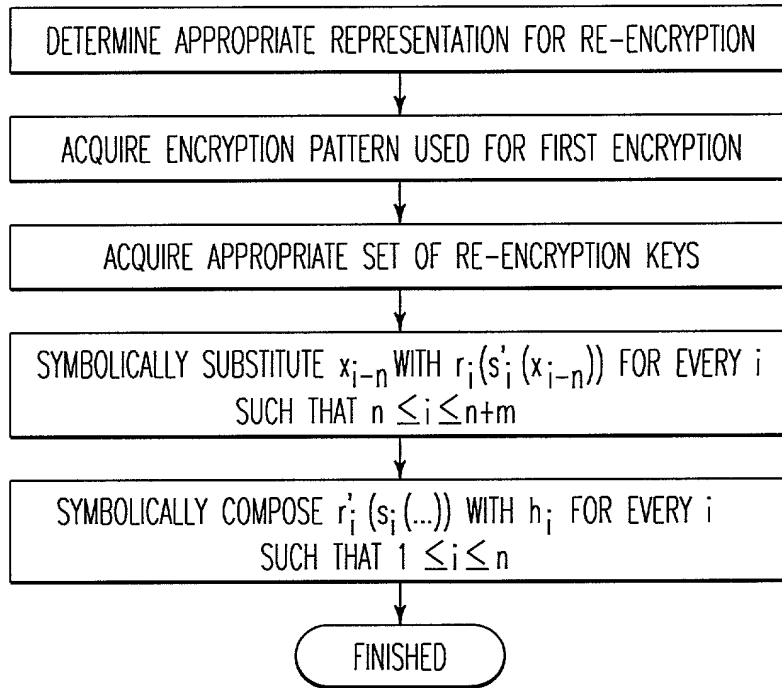


FIG. 54

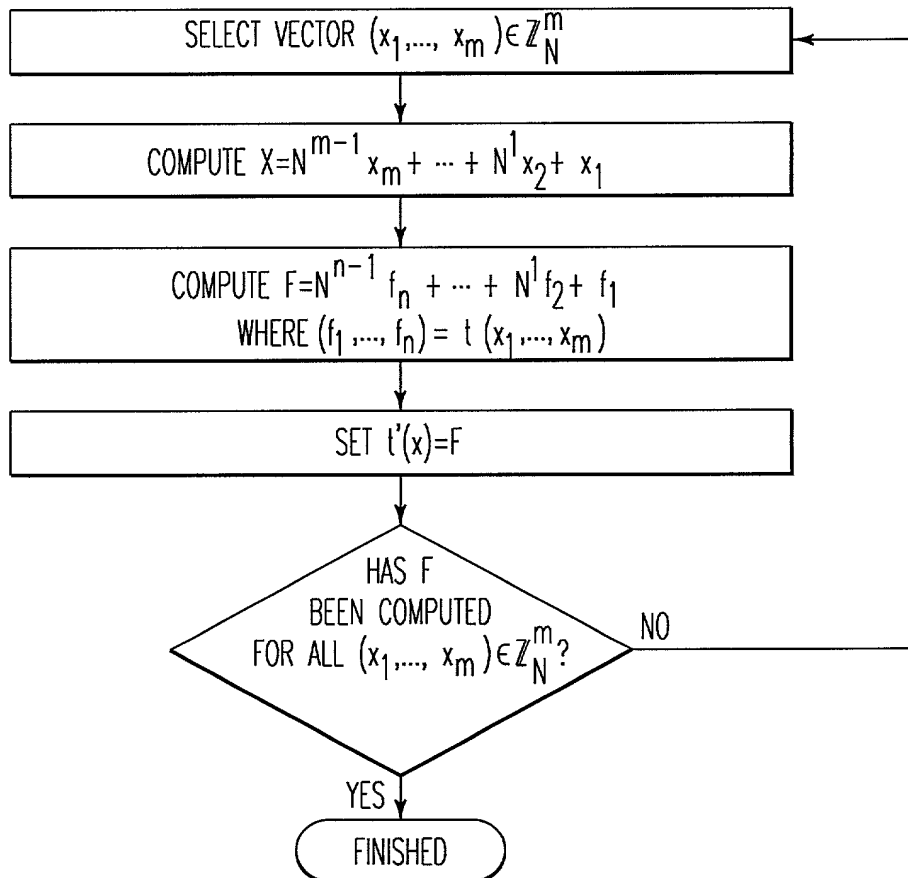


FIG. 55

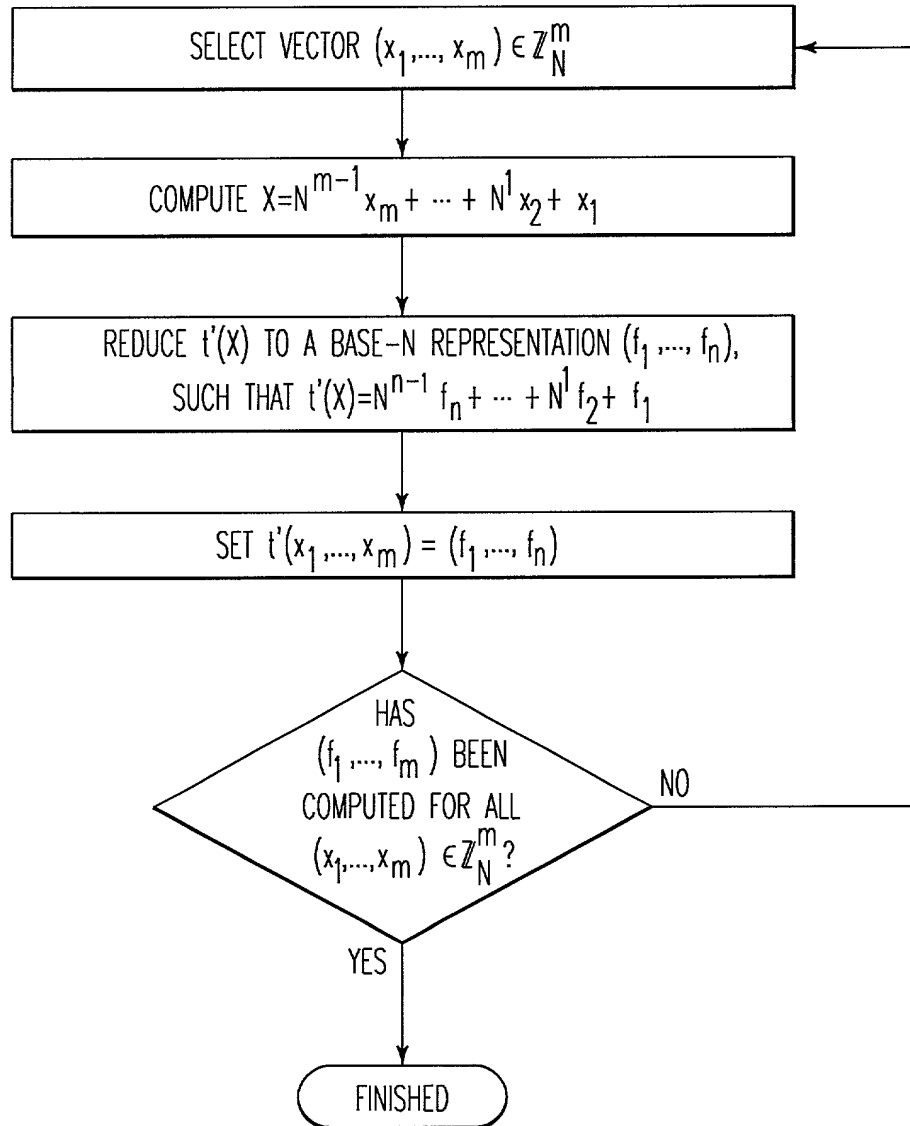


FIG. 56

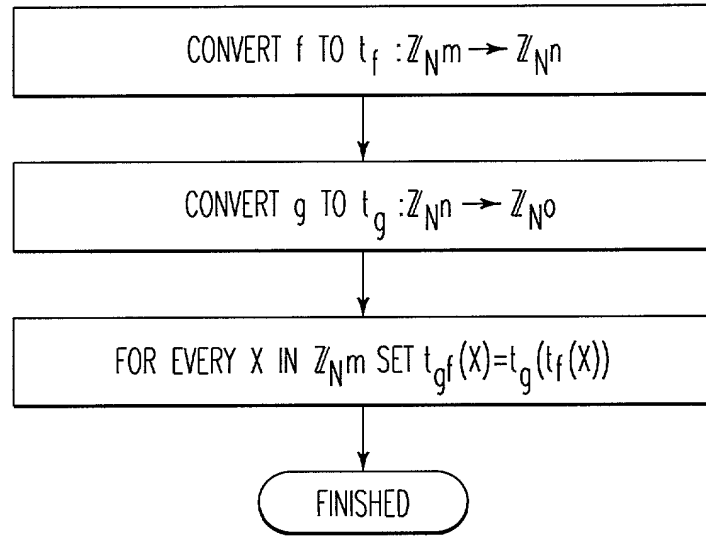


FIG. 57

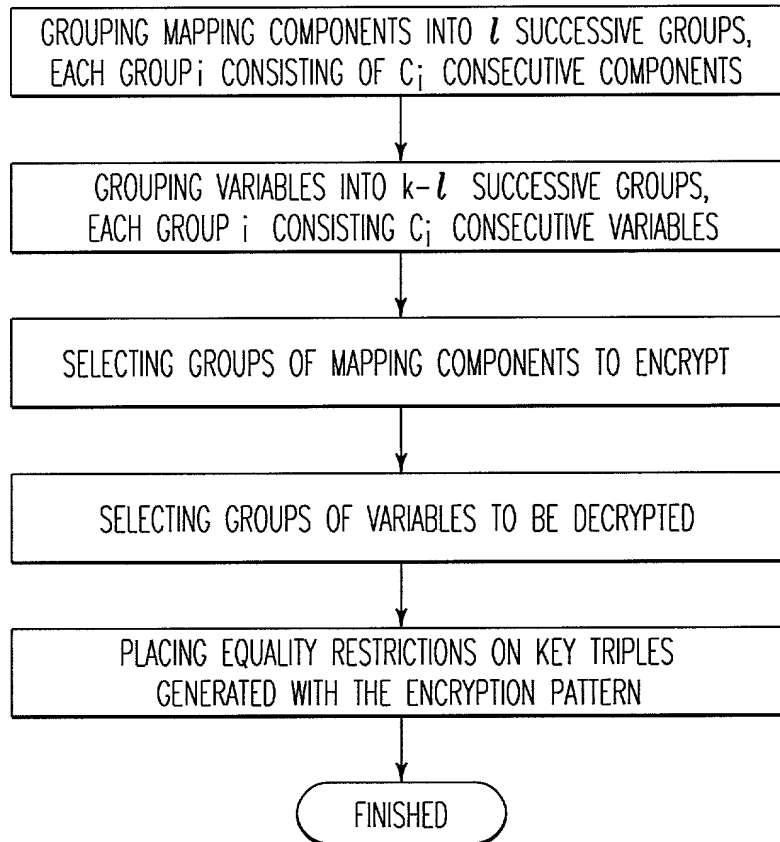


FIG. 58

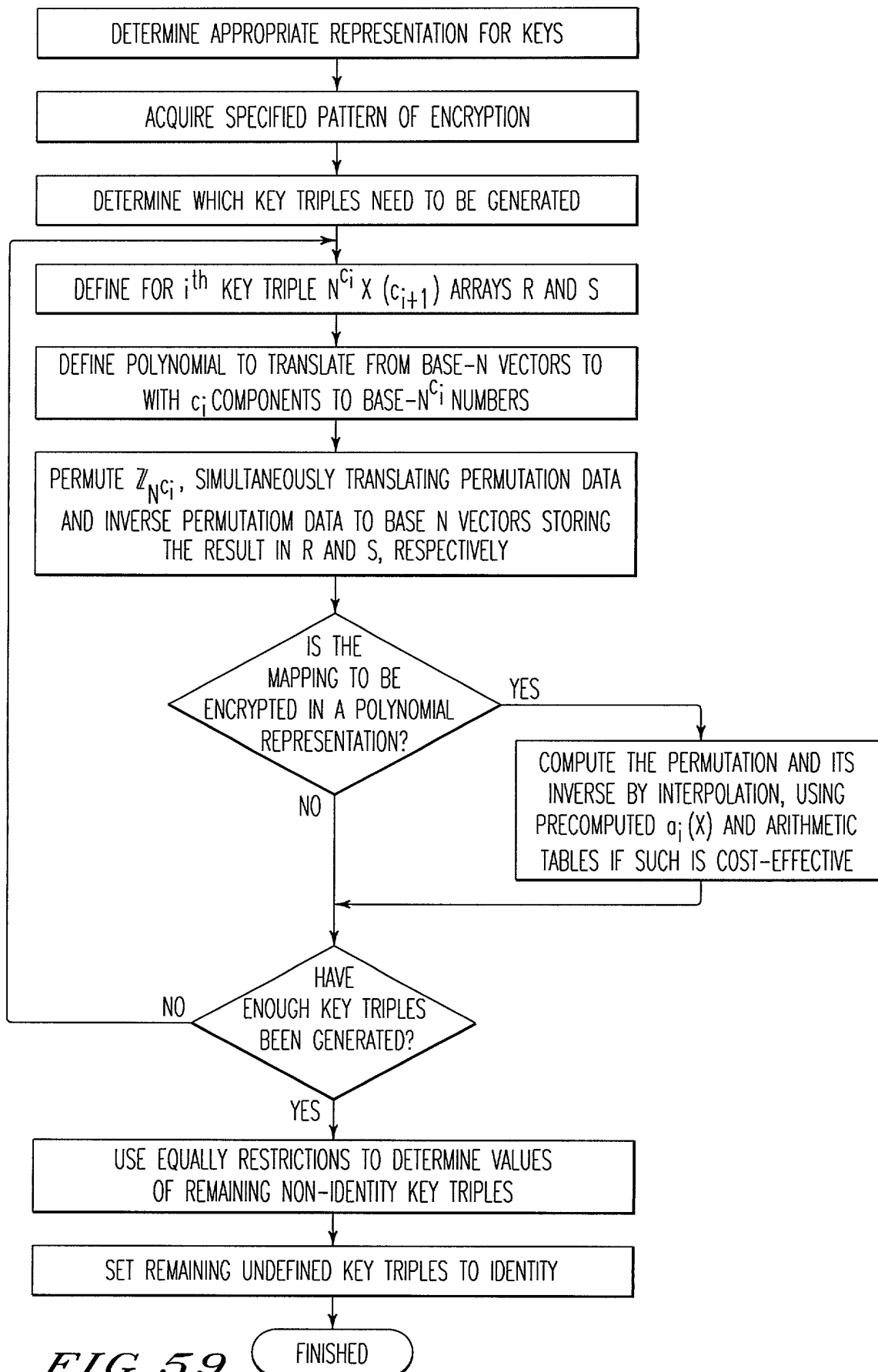


FIG. 59

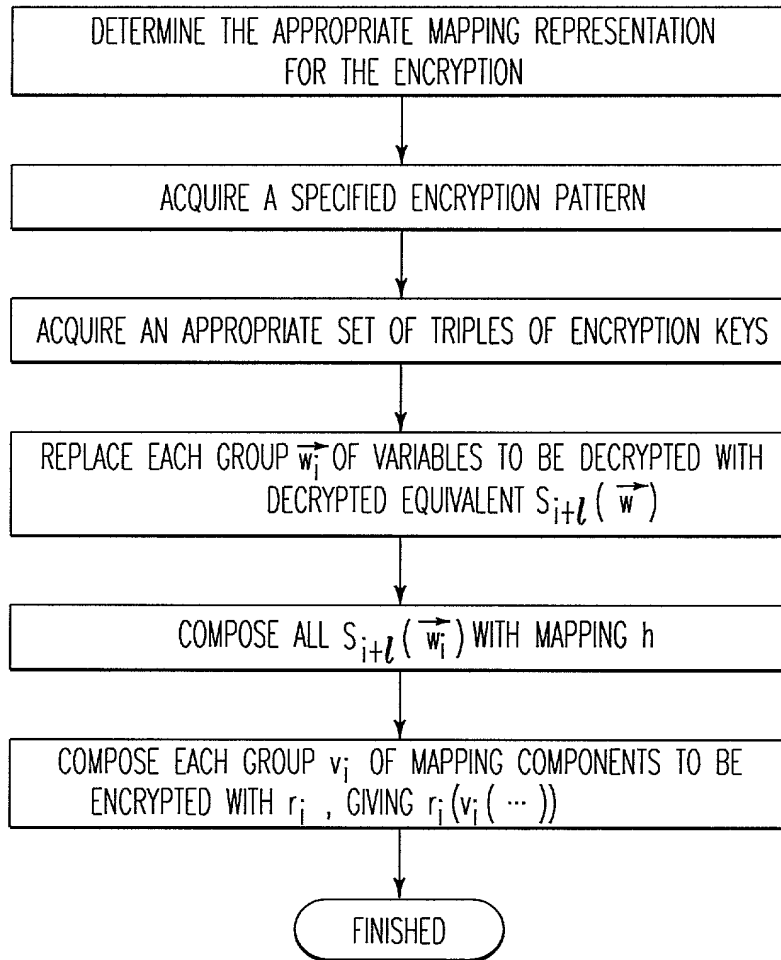


FIG. 60

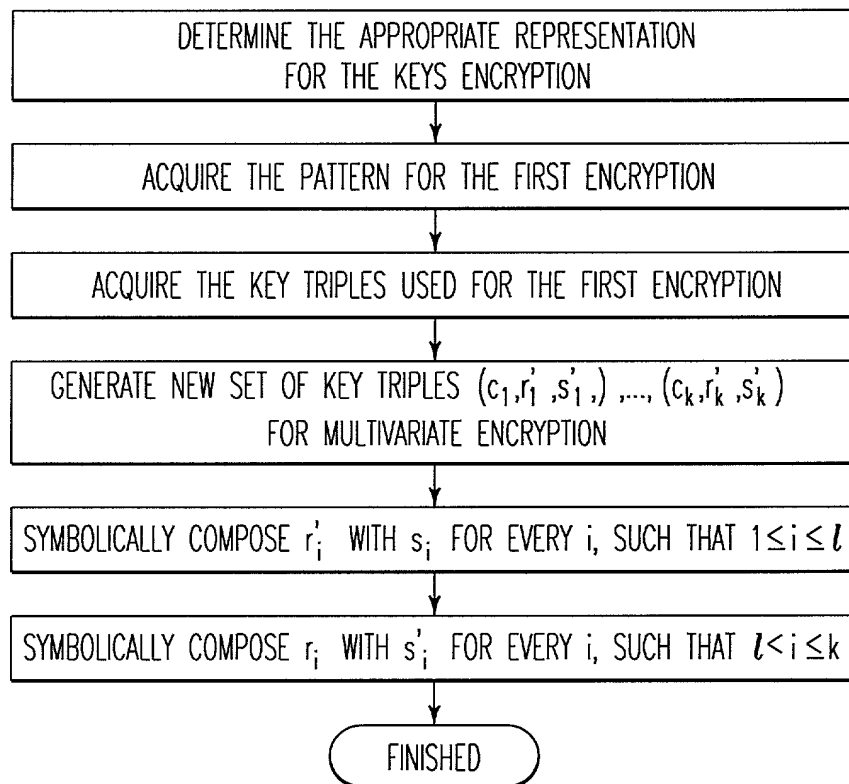


FIG. 61

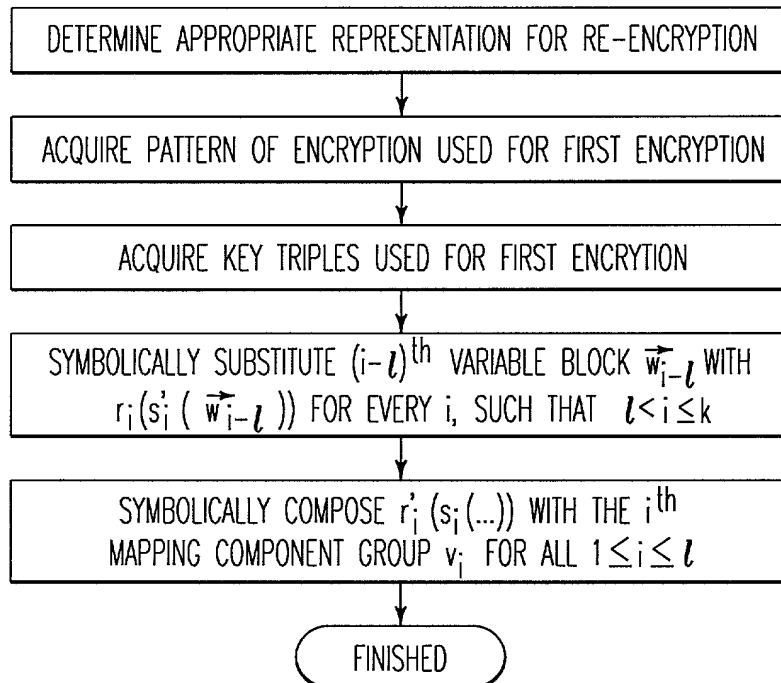


FIG. 62

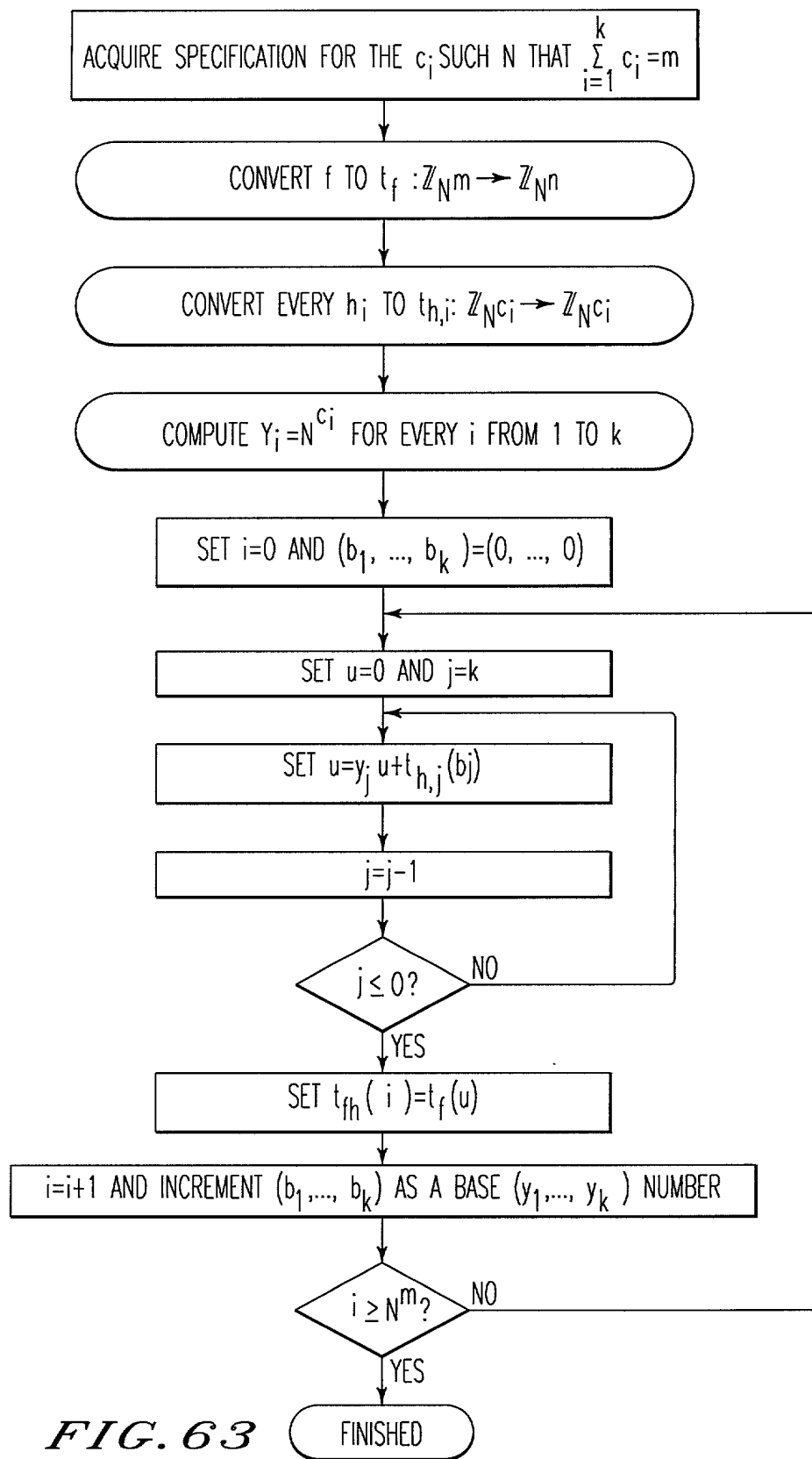


FIG. 63

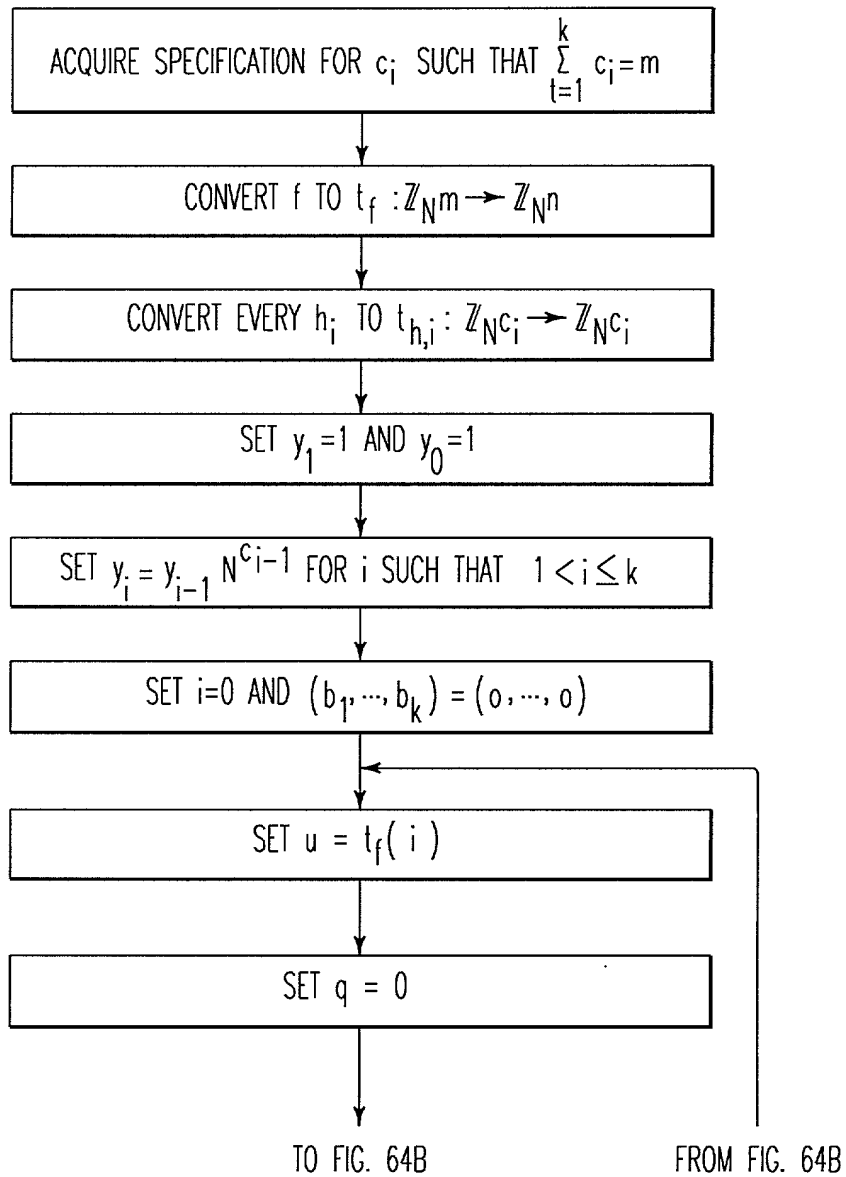


FIG. 64A

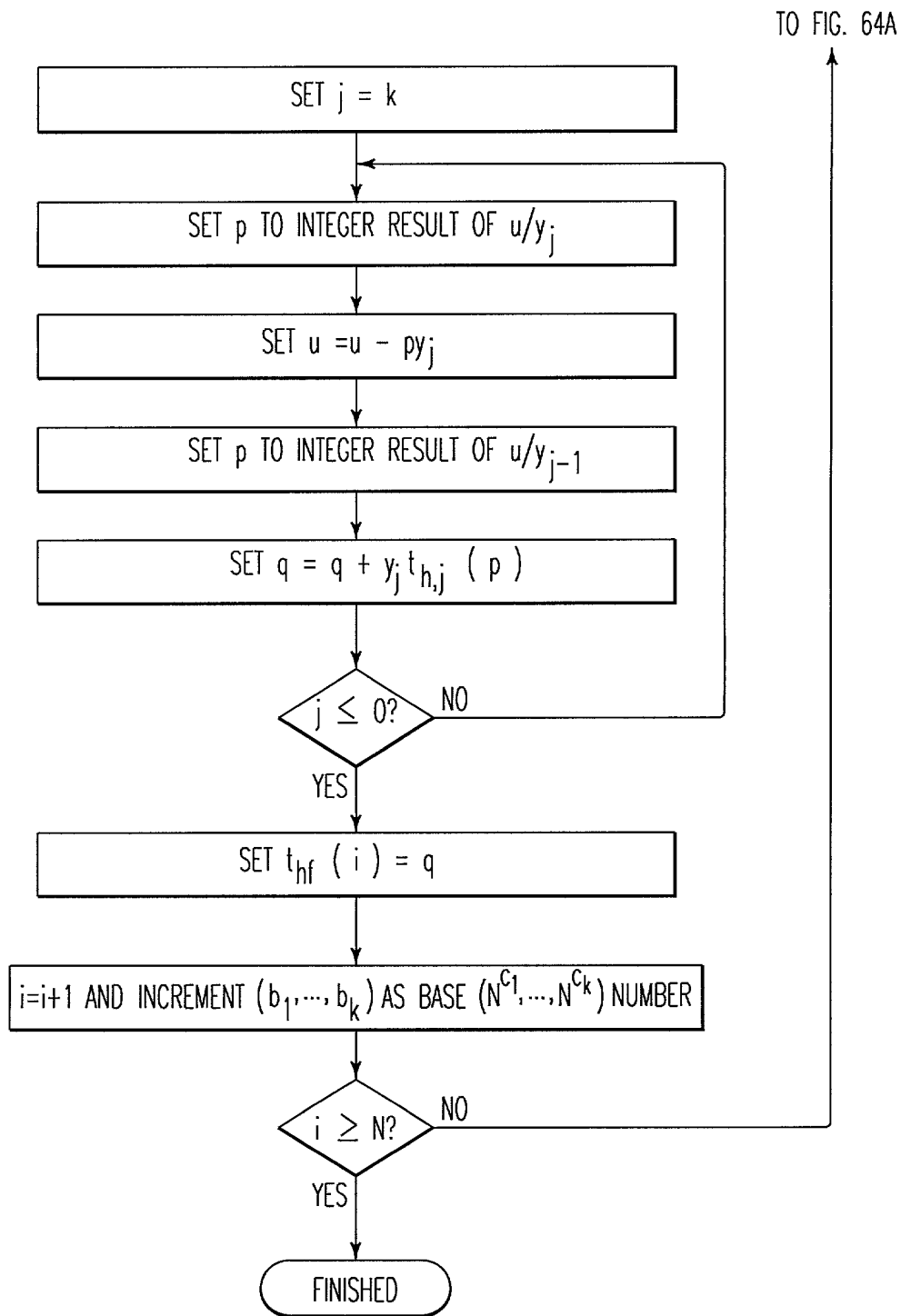


FIG. 64B

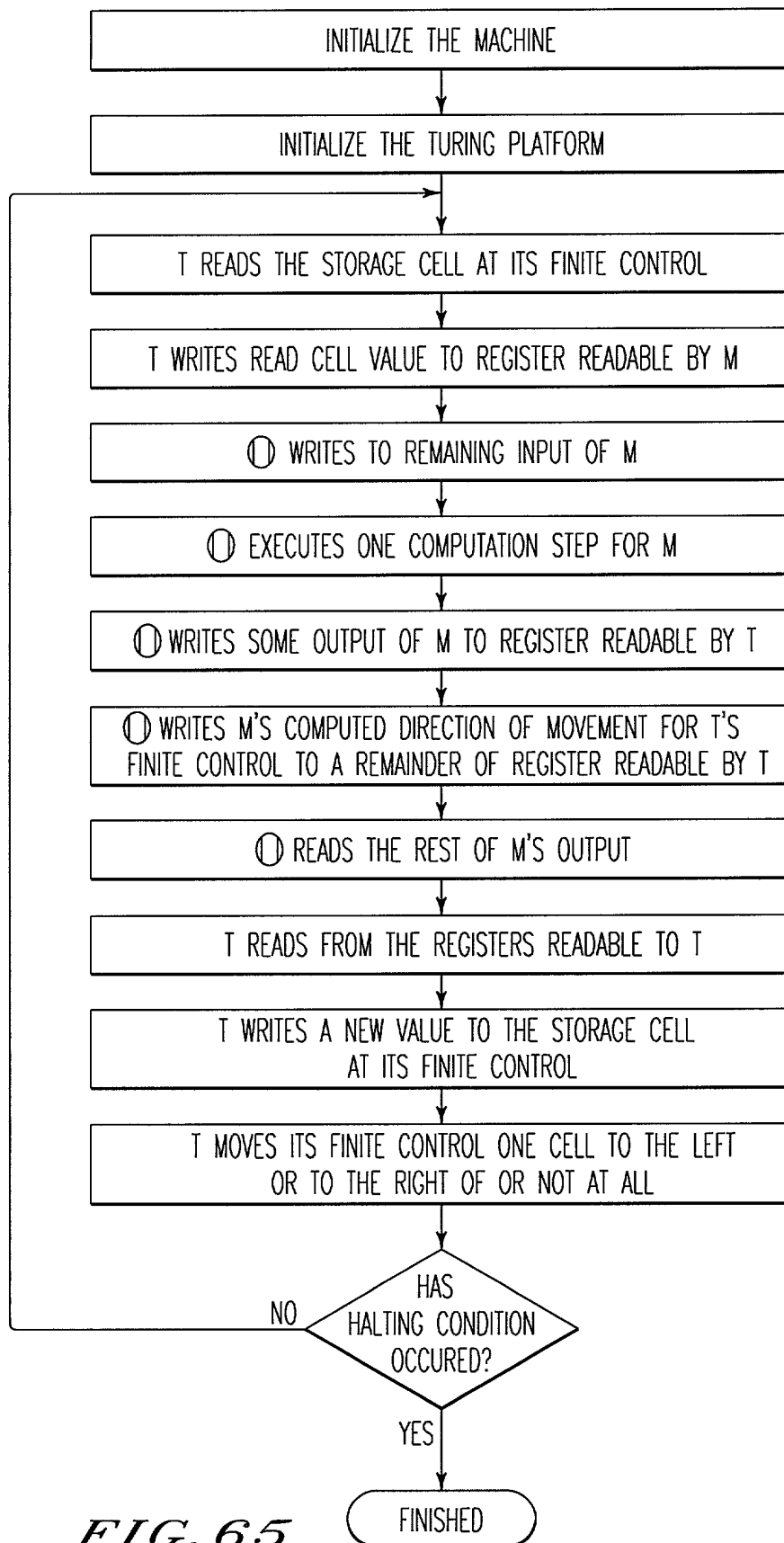


FIG. 65

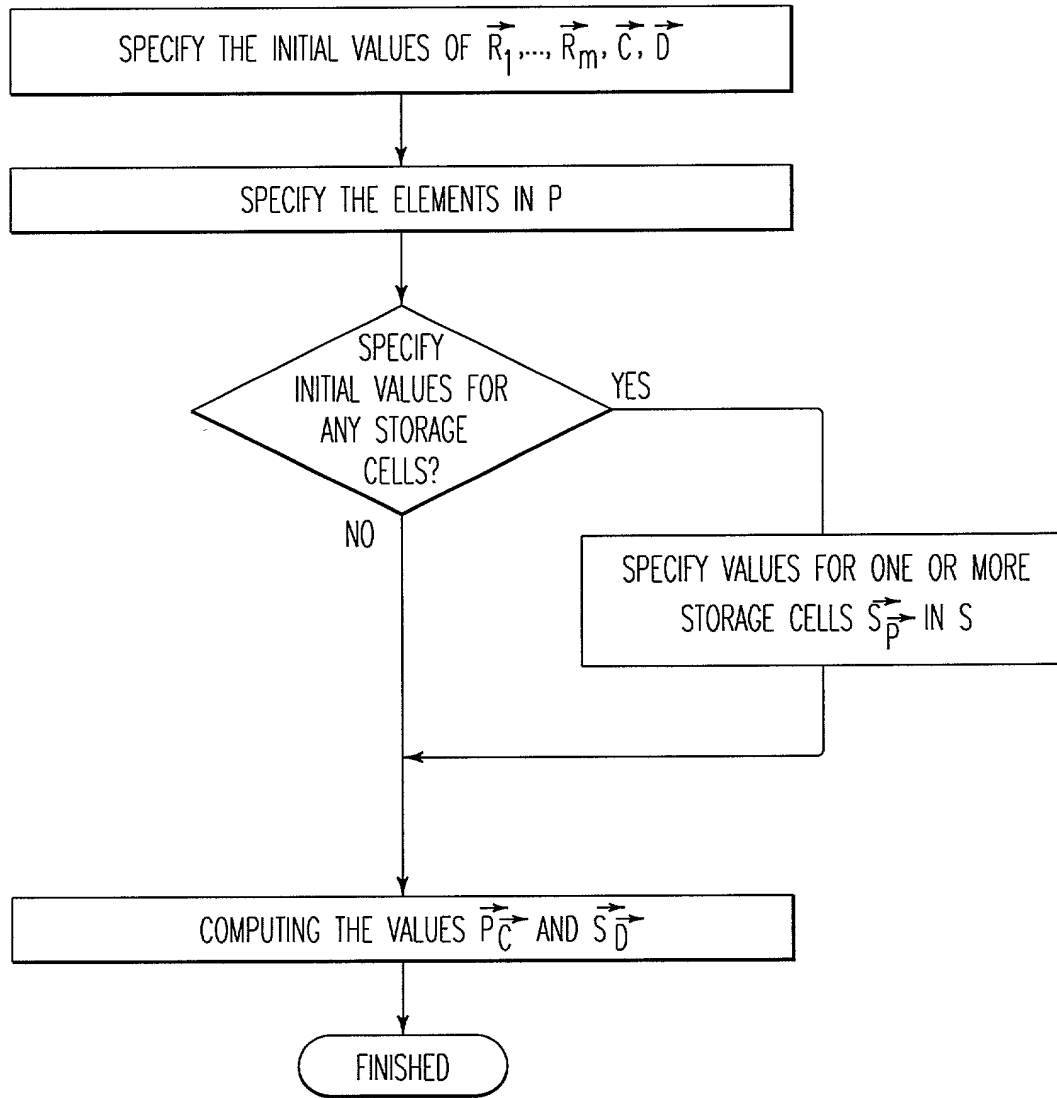


FIG. 66

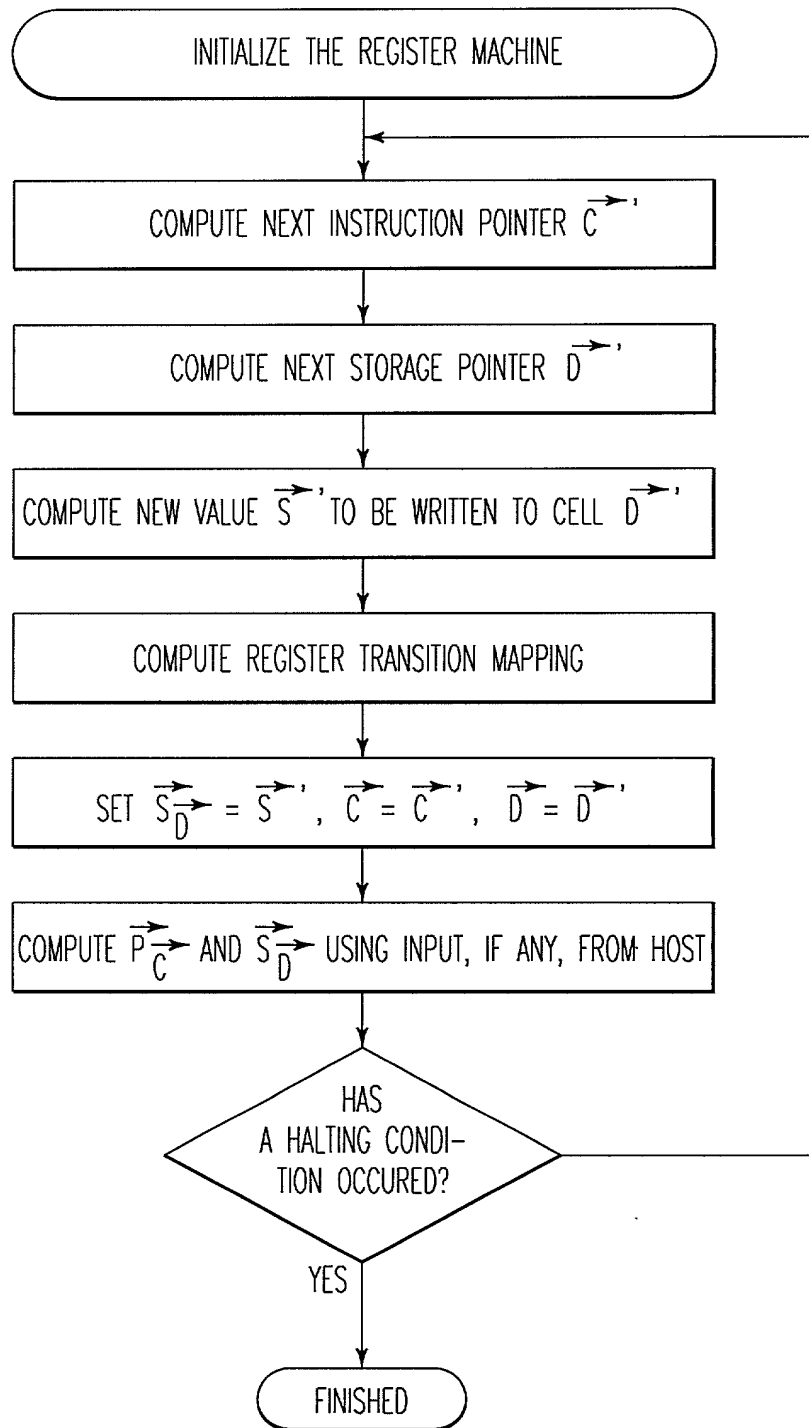


FIG. 67

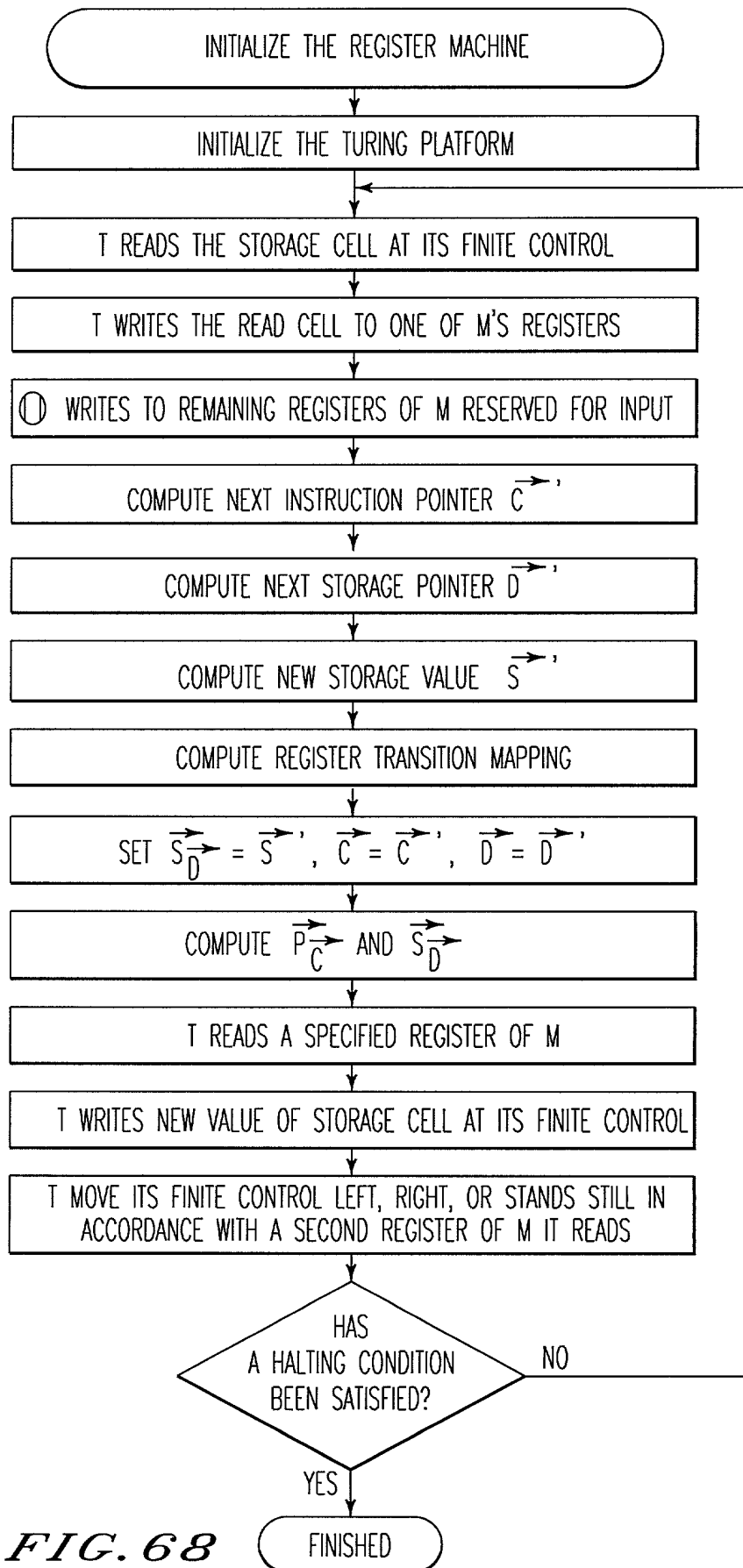


FIG. 68

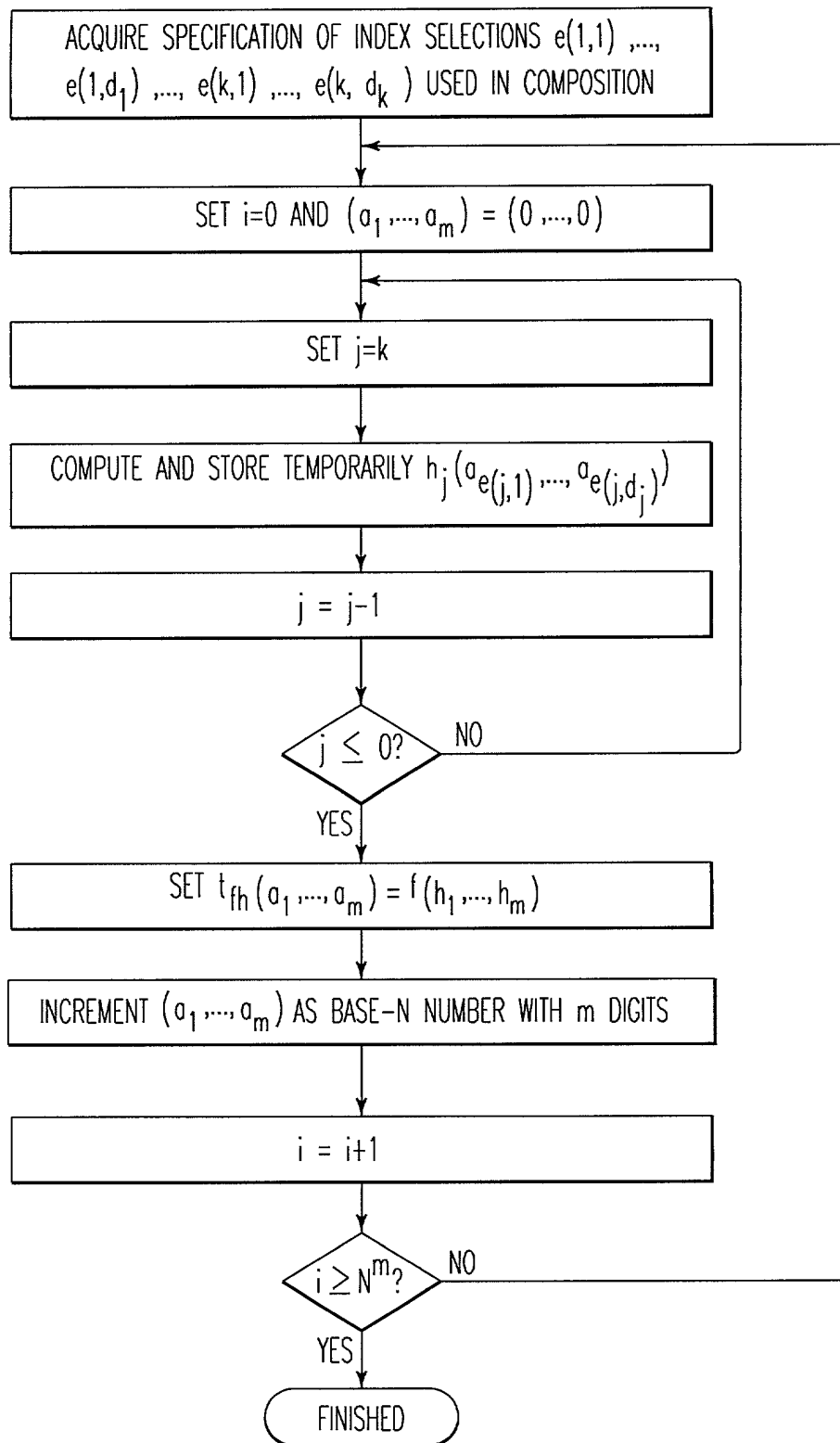


FIG. 69

```

graph TD
    A[ACQUIRE SPECIFICATION OF INDEX SELECTIONS  $e'(1,1), \dots, e'(1,c_1), \dots, e'(k,1), \dots, e'(k,c_k)$ ] --> B[ACQUIRE SPECIFICATION OF INDEX SELECTIONS  $e(1,1), \dots, e(1,d_1), \dots, e(k,1), \dots, e(k,d_k)$ ]
    B --> C[SET  $i=0$  AND  $(a_1, \dots, a_m) = (0, \dots, 0)$ ]
    C --> D[SET  $j=k$ ]
    D --> E[COMPUTE AND STORE TEMPORARILY  $h_j(f_{e'(j,1)}, \dots, f_{e'(j,c_j)}), x_{e(j,1)}, \dots, x_{e(j,d_j)})$ ]
    E --> F[ $j = j-1$ ]
    F --> G{ $j \leq 0$ ?}
    G -- NO --> D
    G -- YES --> H[SET  $t_{fh}(a_1, \dots, a_m) = (h_1, \dots, h_k)$ ]
    H --> I[ $i=i+1$  AND INCREMENT  $(a_1, \dots, a_m)$  AS BASE-N NUMBER WITH  $m$  DIGITS]
    I --> J[ $i = i+1$ ]
    J --> K{ $i \geq N^m$ ?}
    K -- NO --> A
    K -- YES --> L([FINISHED])

```

FIG. 70

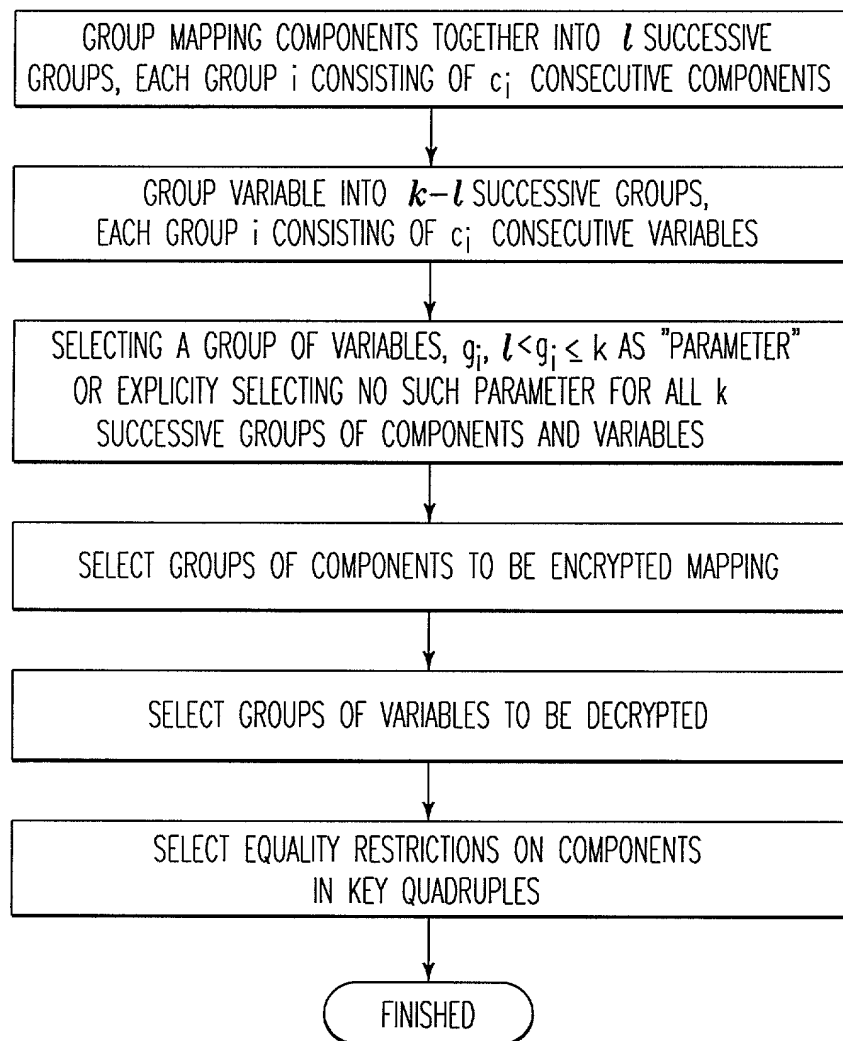


FIG. 71

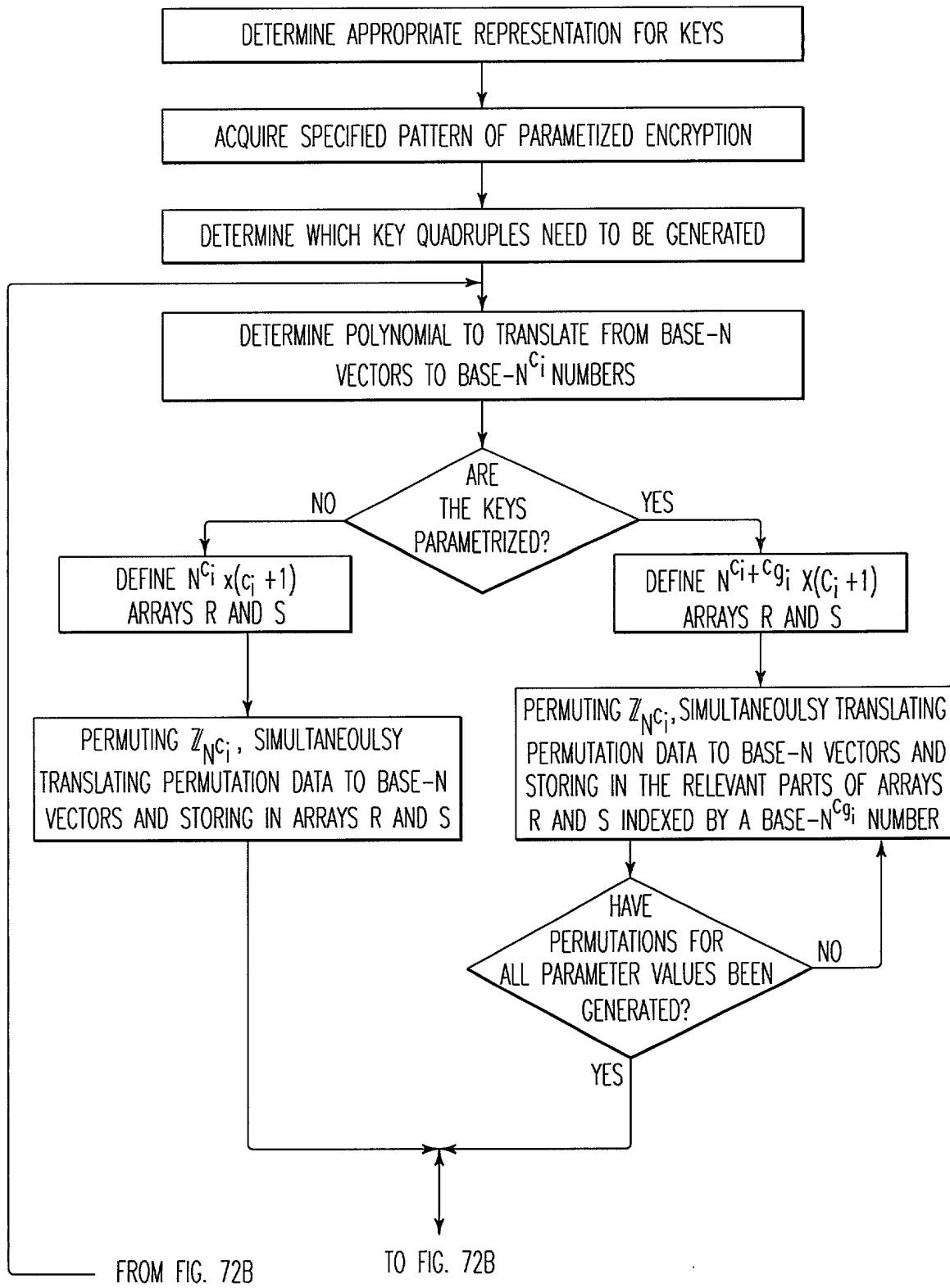


FIG. 72A

TO FIG. 72A

FROM FIG. 72A

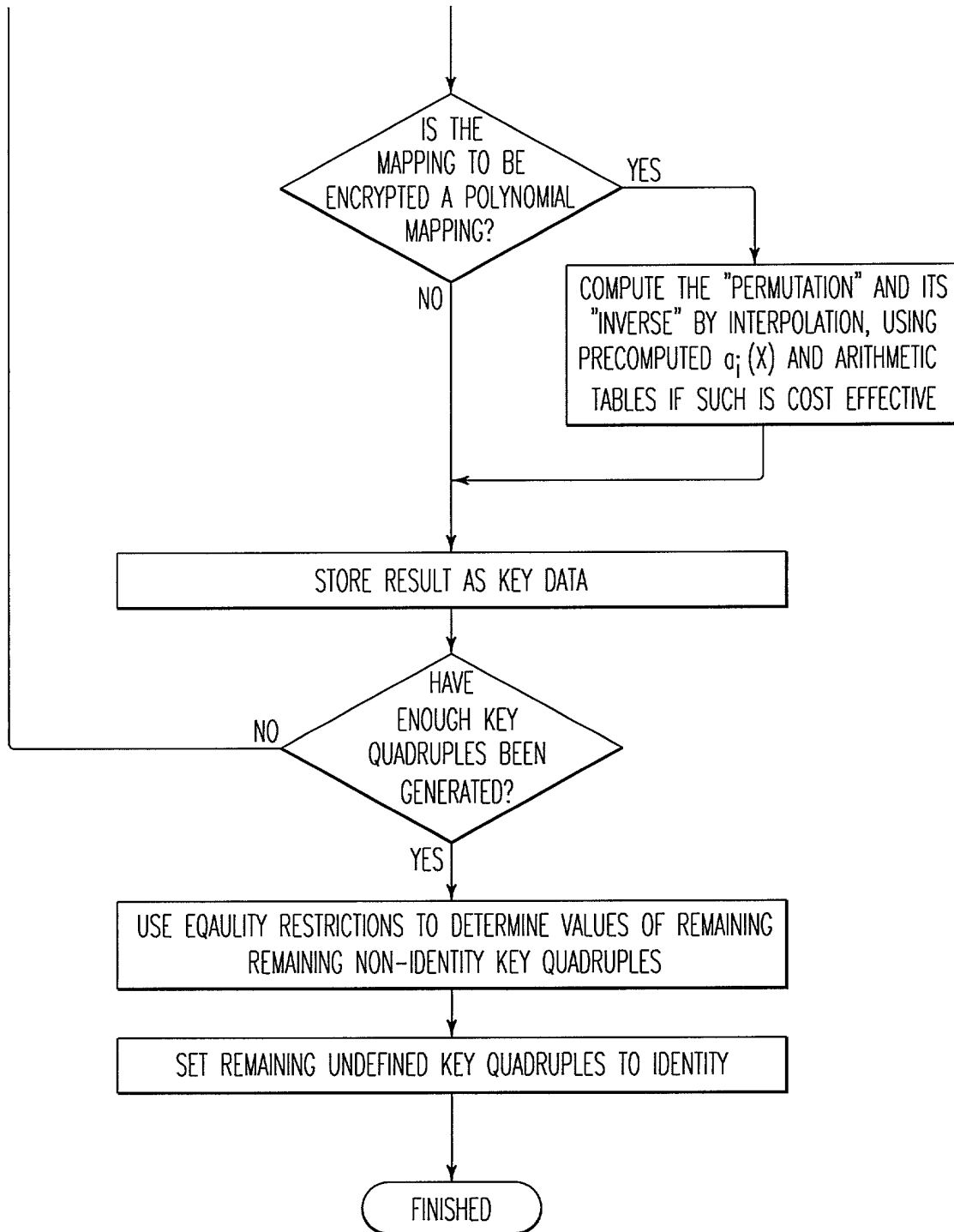


FIG. 72B

```

graph TD
    A[DETERMINE APPROPRIATE MAPPING REPRESENTATION  
FOR THE ENCRYPTION] --> B[ACQUIRE A SPECIFIED PATTERN OF PARAMETIZED ENCRYPTION]
    B --> C[ACQUIRE AN APPROPRIATE SET OF QUADRUPLES OF ENCRYPTION KEYS]
    C --> D[SYMBOLICALLY SUBSTITUTE EACH GROUP OF VARIABLES  $\vec{w}_{i-l}$ , TO BE  
DECRYPTED IN A PARAMETIZED MANNER, WITH  $s_i(\vec{w}_{i-l}, \vec{w}_{g_i-l})$ ]
    D --> E[SYMBOLICALLY SUBSTITUTE EACH GROUP OF VARIABLES  $\vec{w}_{i-l}$ , TO BE  
DECRYPTED IN A NON-PARAMETIZED MANNER, WITH  $s_i(\vec{w}_{i-l})$ ]
    E --> F[COMPOSE EACH GROUP OF MAPPING COMPONENTS  $v_i$  TO BE ENCRYPTED  
IN A PARAMETIZED MANNER, WITH  $r_i$ , GIVING  $r_i(v_i(\dots), \vec{w}_{g_i-l})$ ]
    F --> G[COMPOSE EACH GROUP OF MAPPING COMPONENTS  $v_i$  TO BE ENCRYPTED  
IN A NON-PARAMETIZED MANNER, WITH  $r_i$ , GIVING  $r_i(v_i(\dots))$ ]
    G --> H([FINISHED])
  
```

FIG. 73

```

graph TD
    Start([SPECIFY PATTERN FOR PARAMETRIZED ENCRYPTION OF REGISTER MACHINES MAPPING FOR COMPUTING A COMPUTATION STEP]) --> SetC[SET ALL  $c_i = d$ ]
    SetC --> MarkNext[MARK NEXT INSTRUCTION POINTER AND NEXT STORAGE MAPPINGS AS PLAIN TEXT MAPPINGS]
    MarkNext --> MarkRegisters[MARK SOME REGISTERS AS UNENCRYPTED]
    MarkRegisters --> MarkKey[MARK KEY QUADRUPLES FOR PLAIN TEXT REGISTER & POINTER MAPPINGS AS IDENTITY MAPPINGS]
    MarkKey --> MarkEncryption[MARK ANY ENCRYPTION OF PARTS OF THE REGISTER TRANSITION MAPPING, AND ANY REGISTERS AS NON-PARAMETRIZED]
    MarkEncryption --> MarkStorage[MARK THE STORAGE CELL MAPPING  $q$  FOR PARAMETRIZED ENCRYPTION]
    MarkStorage --> MarkCells[MARK ONE OR MORE "CELLS" IN THE STORAGE SPACE AS PLAIN TEXT "CELLS"]
    MarkCells --> Finished([FINISHED])
  
```

FIG. 74

```

graph TD
    A[DETERMINE APPROPRIATE REPRESENTATION FOR THE KEYS] --> B[ACQUIRE SPECIFIED SPECIALIZED PATTERN OF PARAMETIZED REGISTER MACHINE ENCRYPTION]
    B --> C[DEFINE TWO  $N^{d+d} \times (d+1)$  ARRAYS R AND S]
    C --> D[DEFINE POLYNOMIAL TO TRANSLATE FROM BASE-N VECTORS TO BASE- $N^d$  NUMBERS]
    D --> E{IS STORAGE CELL # i ENCRYPTED?}
    E -- YES --> F[PERMUTING  $\mathbb{Z}_{N^d}$ , SIMULTANEOUSLY TRANSLATING PERMUTATION DATA TO BASE-N VECTORS AND STORING IN RELEVANT PARTS OF ARRAYS R AND S INDEXED BY BASE  $N^d$  NUMBER REPRESENTING A CELL INDEX]
    E -- NO --> G[FILL RELEVANT PART OF R AND S WITH DATA FOR IDENTITY MAPPING]
    F --> G
    G --> H{HAVE PERMUTATIONS FOR ALL STORAGE CELLS BEEN SET?}
    H -- YES --> I[TO FIG. 75B]
    H -- NO --> E
  
```

FIG. 75A

TO FIG. 75B

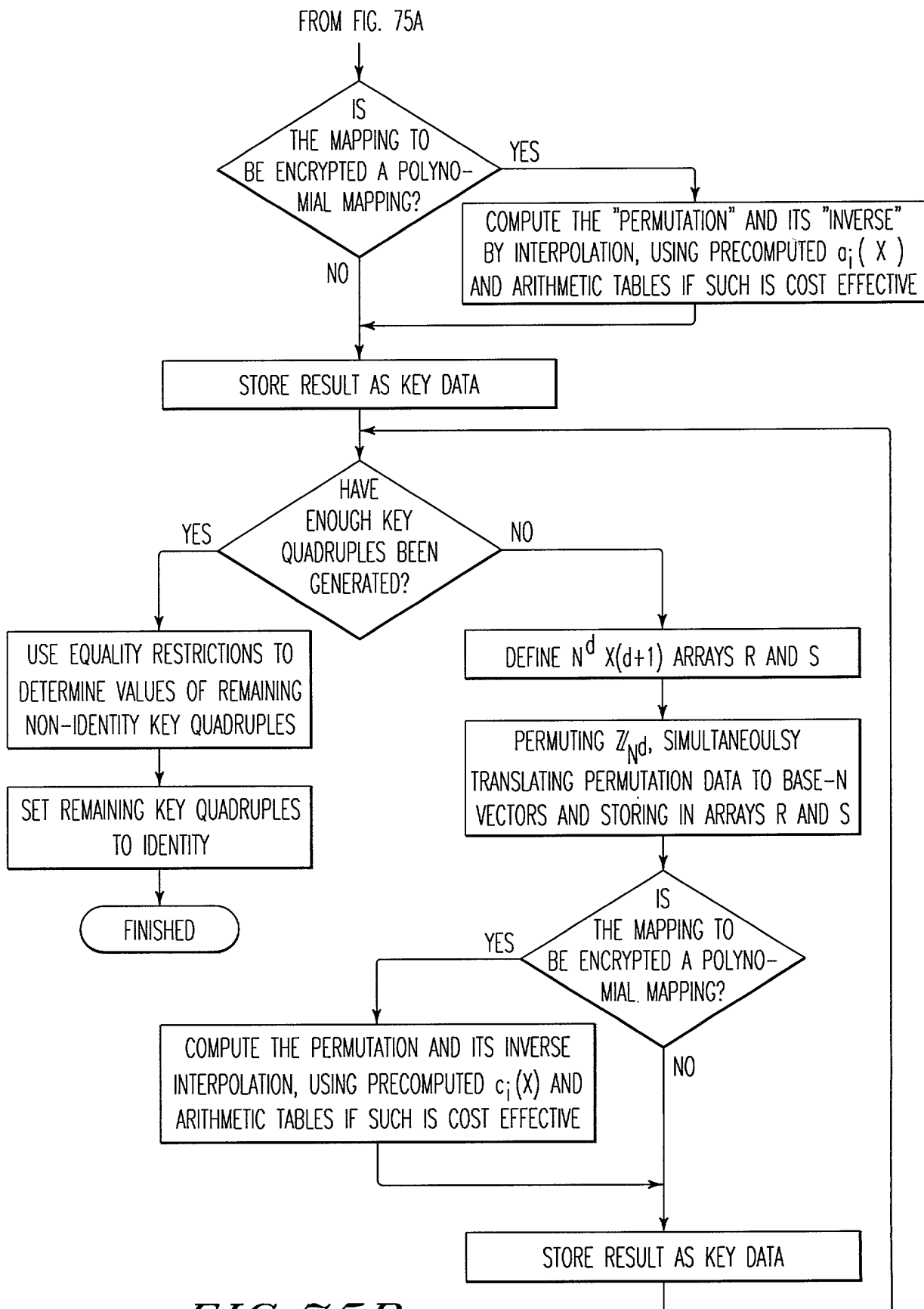


FIG. 75B

```

graph TD
    A[DETERMINE THE APPROPRIATE REPRESENTATION  
FOR THE ENCRYPTION] --> B[ACQUIRE A SPECIFIED PATTERN OF PARAMETIZED ENCRYPTION]
    B --> C[ACQUIRE AN APPROPRIATE SET OF QUADRUPLES OF SPECIALLY  
ADAPTED ENCRYPTION KEYS]
    C --> D[DO PARAMETIZED ENCRYPTION OF REGISTER MACHINE  
MAPPING]
    D --> E([FINISHED])
  
```

FIG. 76